

# Contents

<b>I</b>	<b>Deterministic Control</b>	<b>5</b>
<b>1</b>	<b>Static Optimization</b>	<b>7</b>
1.1	Calculus Reminder . . . . .	7
1.2	Abstract Results . . . . .	8
1.3	Euler Conditions . . . . .	9
1.4	Kuhn–Tucker Theorem . . . . .	11
<b>2</b>	<b>Calculus of Variations</b>	<b>15</b>
2.1	Problem without Terminal Condition . . . . .	17
2.2	Sufficient Condition for Optimality . . . . .	18
2.3	Example: 1-Dimensional Quadratic Problem . . . . .	19
2.4	Example: Optimal Consumption . . . . .	19
<b>3</b>	<b>Maximum Principle</b>	<b>21</b>
3.1	Bolza, Lagrange and Mayer formulation . . . . .	22
3.2	Pontryagin Maximum Principle . . . . .	23
3.3	Sufficient Condition for Optimality . . . . .	25
3.4	Example: Linear Quadratic Regulator . . . . .	27
3.5	Example: Consumption and Savings . . . . .	28
<b>4</b>	<b>Dynamic Programming</b>	<b>31</b>
4.1	Introductory Example . . . . .	32
4.2	Dynamic Programming Principle (DPP) . . . . .	33
4.3	Dynamic Programming Equation (DPE) . . . . .	35
4.4	Verification . . . . .	38
4.5	DPE and Maximum Principle . . . . .	39
4.6	Example: Linear Quadratic Regulator . . . . .	40
4.7	Example: Optimal Consumption . . . . .	41

<b>II</b>	<b>Stochastic Control</b>	<b>43</b>
<b>5</b>	<b>Stochastic Analysis Reminder</b>	<b>45</b>
5.1	Stochastic Differential Equations . . . . .	45
5.2	Feynman–Kac Representation . . . . .	47
<b>6</b>	<b>Dynamic Programming in Standard Form</b>	<b>49</b>
6.1	Dynamic Programming Equation . . . . .	54
6.2	Verification . . . . .	57
6.3	Infinite Time Horizon . . . . .	58
<b>7</b>	<b>Portfolio Choice</b>	<b>63</b>
7.1	Black–Scholes . . . . .	64
7.2	Example with Stochastic Volatility . . . . .	66
7.3	Logarithmic Utility . . . . .	69
<b>8</b>	<b>Optimal Stopping</b>	<b>73</b>
8.1	Essential Supremum . . . . .	73
8.2	Snell Envelope Theory in Discrete Time . . . . .	74
8.3	Snell Envelope Theory in Continuous Time . . . . .	79
8.4	Optimal Stopping of a Diffusion . . . . .	80
8.5	Examples . . . . .	88