

## Lecture 17

Solutions to in-class exercises.

1. Find the QR factorization of  $\begin{pmatrix} 1 & 0 \\ 0 & 1 \\ -1 & 2 \end{pmatrix}$ .

$$\text{Gram-Schmidt: } u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, v_2^\perp = v_2 - (u_1 \cdot v_2) u_1 = \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix} - \frac{-2}{\sqrt{2}} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ -1 & 2 \end{pmatrix} = \underbrace{\begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 0 & 1/\sqrt{2} \\ -1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix}}_Q \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{pmatrix}}_R \right.$$

2. Let  $S = \text{Im}(A)$ . Find the matrix of proj.: matrix of proj is  $QQ^T = \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 0 & 1/\sqrt{2} \\ -1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix} \begin{pmatrix} 1/\sqrt{2} & 0 & -1/\sqrt{2} \\ 0 & 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix}$

$$3. \|T(v)\|^2 = T(v) \cdot T(v) = v \cdot v = \|v\|^2 \xrightarrow{\text{Both are } \geq 0} \|T(v)\| = \|v\|$$

$$((AB)^T)_{ij} = (\text{jth row of } A)^T \cdot (\text{iith col of } B), \text{ and } (B^T A^T)_{ij} = (\text{iith row of } B^T) \cdot (\text{jth col of } A), \text{ so } (AB)^T = B^T A^T.$$

Recap:

- A linear transformation with  $n \times n$  matrix  $Q$  is orthogonal if  $Q = \begin{pmatrix} 1 & & & \\ u_1 & \dots & u_n & | \\ & & & 1 \end{pmatrix}$
- ↪ Equivalently,  $Q^T Q = I_n$  (i.e.  $Q^T = Q^{-1}$ )
- ↪ Equivalently,  $T$  preserves the dot product:  $T(v) \cdot T(w) = v \cdot w$

Today: more on orthogonality + orthogonal diagonalization.

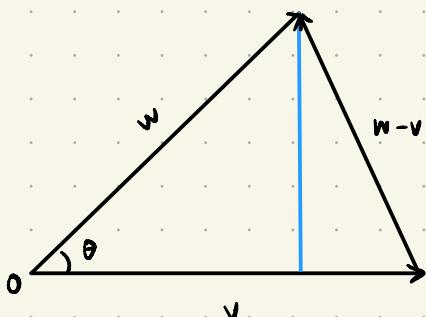
First: how to picture orthogonal transformations

What does it mean geometrically that  $T$  preserves the dot product? We have seen it preserves length.

Now we'll see: if  $T$  is orthogonal, then it preserves angles.

Question: what's the relation between the dot product of  $v$  and  $w$  and their dot product?

Answer: if we put  $v$  and  $w$  on the plane, and  $v$  on the  $x$ -axis of  $\mathbb{R}^2$ , we get:



$$\begin{aligned} \text{Notice first: } \|w-v\|^2 &= (w-v) \cdot (w-v) = v \cdot v + w \cdot w - 2v \cdot w \\ &= \|v\|^2 + \|w\|^2 - 2v \cdot w \quad (*) \end{aligned}$$

On the other hand, the coordinates of  $w$  are, by trigonometry,  $(\|w\|\cos\theta, \|w\|\sin\theta)$ .

the coordinates of  $v$  are clearly  $(\|v\|, 0)$

$$\begin{aligned} \text{So } \|w-v\| &= \|(\|w\|\cos\theta - \|v\|, \|w\|\sin\theta)\| \\ &= (\|w\|\cos\theta - \|v\|)^2 + \|w\|^2\sin^2\theta \\ &\stackrel{\cos^2\theta + \sin^2\theta = 1}{=} \|v\|^2 + \|w\|^2 - 2\|v\|\|w\|\cos\theta \end{aligned}$$

Comparing this with  $(*)$ , we get  $v \cdot w = \|v\|\|w\|\cos\theta$

Upshot: dot product encapsulates lengths + angles, so if  $T$  is orthogonal,

$$\cos(\angle(T(v), T(w))) = \frac{T(v) \cdot T(w)}{\|T(v)\| \|T(w)\|} = \frac{v \cdot w}{\|v\| \|w\|} = \cos(\angle(v, w)).$$

### $2 \times 2$ orthogonal matrices

let  $Q$  be a  $2 \times 2$  orthogonal matrix. Then the columns of  $Q$  are unit vectors at a  $90^\circ$  angle, so



$$\text{rotation by } \theta, \quad Q = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}$$

OR



$$\text{rotation with vectors swapped, } Q = \begin{pmatrix} -\sin\theta & \cos\theta \\ \cos\theta & \sin\theta \end{pmatrix}$$

Observe: these preserve lengths and angles.

Remark: the orthogonal  $3 \times 3$  matrices of determinant 1 represent all possible rotations in 3D-space. They form a group called  $\text{SO}(3)$ , which has important applications in physics and engineering.

## Orthogonal diagonalization

Recall: diagonalizing  $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$  is finding a basis  $B$  such that  $[T]_B$  is diagonal.

Definition 1: Let  $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$  be a linear transformation. Then orthogonally diagonalizing  $T$  is finding an orthonormal basis  $B$  such that  $[T]_B$  is diagonal.

Example 1: let  $A = \begin{pmatrix} 3 & 2 \\ 2 & 0 \end{pmatrix}$ . Eigenvalues: char poly(A) =  $(3-\lambda)(-2)-4 = \lambda^2 - 3\lambda - 4 = (\lambda-4)(\lambda+1)$

$$E_4 = \text{Ker} \begin{pmatrix} -1 & 2 \\ 2 & -4 \end{pmatrix} = \text{Span} \left( \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right) \Rightarrow \text{Orthonormal basis: } u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$E_{-1} = \text{Ker} \begin{pmatrix} 4 & 2 \\ 2 & 1 \end{pmatrix} = \text{Span} \left( \begin{pmatrix} 1 \\ -2 \end{pmatrix} \right) \Rightarrow \text{Orthonormal basis: } u_2 = \frac{1}{\sqrt{5}} \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

"Luckily",  $u_1$  and  $u_2$  are orthogonal:  $u_1 \cdot u_2 = \frac{1}{\sqrt{5}} (2 \cdot 1 + 1 \cdot (-2)) = 0 \Rightarrow u_1, u_2$  are an orthonormal basis of eigenvectors.

Bonus: Easy to diagonalize! let  $Q = \begin{pmatrix} 2/\sqrt{5} & 1/\sqrt{5} \\ 1/\sqrt{5} & -2/\sqrt{5} \end{pmatrix}$ . Then

$$A = Q \begin{pmatrix} 4 & 0 \\ 0 & 1 \end{pmatrix} Q^{-1} = Q \begin{pmatrix} 4 & 0 \\ 0 & 1 \end{pmatrix} Q^T$$

$$= \begin{pmatrix} 2/\sqrt{5} & 1/\sqrt{5} \\ 1/\sqrt{5} & -2/\sqrt{5} \end{pmatrix} \begin{pmatrix} 4 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 2/\sqrt{5} & 1/\sqrt{5} \\ 1/\sqrt{5} & -2/\sqrt{5} \end{pmatrix}$$

Orthogonal diagonalization of A

Recall:  $A$  is diagonalizable  $\Leftrightarrow \sum g_\lambda = n$ .

Obvious question: when is  $A$  orthogonally diagonalizable?

Observe that if  $A = Q D Q^T$ , then  $A^T = Q D Q^T = A$ .

Definition 2: An  $n \times n$  matrix is symmetric iff  $A^T = A$ .

So, orthogonally diagonalizable matrices are definitely symmetric. Now, which symmetric matrices are orthogonally diagonalizable?

Answer: amazingly, all of them.

Theorem 1 (Spectral theorem): Let  $A$  be an  $n \times n$  symmetric matrix. Then

- 1) The eigenvalues of  $A$  are real and  $\sum_{\lambda \text{ eig. of } A} \lambda = n$
- 2) The eigenspaces of  $A$  are mutually orthogonal (if  $v \in E_\lambda$ ,  $w \in E_\mu$ ,  $\lambda \neq \mu$ , then  $v \cdot w = 0$ )
- 3)  $A$  is orthogonally diagonalizable.

Proof: 1) Consider the eigenvalues of  $A$  over  $\mathbb{C}$ ,  $\lambda_1, \dots, \lambda_n$ . By the "fundamental" theorem of algebra,  $\lambda_1 + \dots + \lambda_n = n$ . So it suffices to show that  $\lambda_1, \dots, \lambda_n$  are actually real. So take one of the eigenvalues  $\lambda = a + bi$ . We want to show that  $b=0$ .

Now, take an eigenvector  $v+iw \in E_\lambda$ . Then

$$\begin{aligned} \underbrace{(v+iw)^T A (v-iw)}_{(a-bi)(v-iw)} &= (a-bi)(v+iw)^T (v-iw) \\ &\quad \downarrow \Rightarrow a-bi = a+bi \text{ i.e. } b=0. \\ \underbrace{(v+iw)^T A (v-iw)}_{(A^T(v+iw))^T} &= (a+bi)(v+iw)^T (v-iw) \\ &\quad \text{A symmetric} \quad \underbrace{(a+bi)(v+iw)}_{(a+bi)(v+iw)} \end{aligned}$$

2) Similar trick: if  $v \in E_\lambda$  and  $w \in E_\mu$ ,

$$\begin{aligned} v^T A w &= v^T (Aw) = \mu v^T w \\ v^T A w &= (Av)^T w = \lambda v^T w \end{aligned} \quad \left| \begin{array}{l} \text{since } \lambda \neq \mu, v^T w = 0 \end{array} \right.$$

3) Proof for  $n=2$ : take an eigenvector  $v$  and complete it to an orthonormal basis  $B$ :  $u_1, u_2$ .

Then  $A = Q^T \begin{pmatrix} \lambda & * \\ 0 & * \end{pmatrix} Q$ . Now notice that  $\begin{pmatrix} \lambda & * \\ 0 & * \end{pmatrix} = QAQ^T$ , and the RHS is symmetric:  $(QAQ^T)^T = QA^TQ^T = QAQ^T$ . It follows that  $\begin{pmatrix} \lambda & * \\ 0 & * \end{pmatrix} = \begin{pmatrix} \lambda & 0 \\ 0 & \mu \end{pmatrix}$ , as we wanted.

Proof for  $n=3$ : take an eigenvector and complete it to an orthonormal basis  $u_1, u_2, u_3$ .

Then  $A = Q^T \begin{pmatrix} \lambda & * & * \\ 0 & * & * \\ 0 & * & * \end{pmatrix} Q$ . Same argument  $\Rightarrow A = \begin{pmatrix} \lambda & 0 & 0 \\ 0 & \boxed{B} \\ 0 & 0 \end{pmatrix}$ . Now by the previous case,  $B = Q_0^T D Q_0$ , so  $A = Q^T Q_0^T \begin{pmatrix} \lambda & 0 & 0 \\ 0 & M_1 & 0 \\ 0 & 0 & M_2 \end{pmatrix} Q_0 Q$ , as desired.

## Algorithm for orthogonal diagonalization

1. Is  $A$  symmetric? If not,  $A$  is not orthogonally diagonalizable.

2. Find an eigenbasis (always possible)

3. Find an orthonormal basis for each eigenspace.

Example 2: Orthogonally diagonalize the matrix  $A = \begin{pmatrix} 5/4 & 0 & \sqrt{3}/4 \\ 0 & 1 & 0 \\ \sqrt{3}/4 & 0 & 3/4 \end{pmatrix}$

$$\text{char poly } (A) = \det \begin{pmatrix} 5/4 - \lambda & 0 & \sqrt{3}/4 \\ 0 & 1 - \lambda & 0 \\ \sqrt{3}/4 & 0 & 3/4 - \lambda \end{pmatrix}$$

$$= (1 - \lambda) \cdot \det \begin{pmatrix} 5/4 - \lambda & \sqrt{3}/4 \\ \sqrt{3}/4 & 3/4 - \lambda \end{pmatrix} = (1 - \lambda) \cdot (\lambda^2 - 3\lambda + \frac{35}{16} - \frac{3}{16}) = (1 - \lambda)^2(2 - \lambda)$$

$$E_2 = \ker(A - 2I_3) = \ker \begin{pmatrix} -3/4 & 0 & \sqrt{3}/4 \\ 0 & -1 & 0 \\ \sqrt{3}/4 & 0 & -1/4 \end{pmatrix} = \text{Span} \left( \begin{pmatrix} 1 \\ 0 \\ \sqrt{3} \end{pmatrix} \right) \rightarrow \text{Orthonormal basis: } \frac{1}{2} \begin{pmatrix} 1 \\ 0 \\ \sqrt{3} \end{pmatrix}$$

$$E_1 = \ker(A - I_3) = \ker \begin{pmatrix} 1/4 & 0 & \sqrt{3}/4 \\ 0 & 0 & 0 \\ \sqrt{3}/4 & 0 & 3/4 \end{pmatrix} = \text{Span} \left( \begin{pmatrix} 1 \\ 1 \\ -\sqrt{3} \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right)$$

Next, Gram-Schmidt for the basis  $v_1 = \begin{pmatrix} 1 \\ 1 \\ -\sqrt{3} \end{pmatrix}$ ,  $v_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$  of  $E_1$ :

$$u_1 = \frac{1}{\sqrt{5}} \begin{pmatrix} 1 \\ 1 \\ -\sqrt{3} \end{pmatrix}, \quad v_2^\perp = v_2 - (u_1 \cdot v_2) u_1 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} - \frac{1}{5} \begin{pmatrix} 1 \\ 1 \\ -\sqrt{3} \end{pmatrix} = \frac{1}{5} \begin{pmatrix} -1 \\ 4 \\ \sqrt{3} \end{pmatrix}, \quad u_2 = \frac{1}{2\sqrt{5}} \begin{pmatrix} -1 \\ 4 \\ \sqrt{3} \end{pmatrix}$$

Finally,

$$A = \begin{pmatrix} 1/2 & 1/\sqrt{5} & -1/2\sqrt{5} \\ 0 & 1/\sqrt{5} & 2/\sqrt{5} \\ 1/\sqrt{3} & -\sqrt{3}/\sqrt{5} & \sqrt{3}/2\sqrt{5} \end{pmatrix} \begin{pmatrix} 1 & & \\ & 2 & \\ & & 2 \end{pmatrix} \begin{pmatrix} 1/2 & 0 & 1/\sqrt{3} \\ 1/\sqrt{5} & 1/\sqrt{5} & -\sqrt{3}/\sqrt{5} \\ -1/2\sqrt{5} & 2/\sqrt{5} & \sqrt{3}/2\sqrt{5} \end{pmatrix}$$

In-class exercises:

1. Prove that an orthogonal matrix must have determinant 1 or -1.

2. Find the orthogonal diagonalization of  $\begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$