

Lecture 9 Moment maps in symplectic geometry & gauge theory

(1)

electromagnetism: U(1)-gauge theory

= classical mechanics: symplectic geometry.

Def A symplectic mfd (M^{2n}, ω) is a smooth mfd equipped with $\omega \in \mathcal{Q}^2(M)$ s.t

- 1) $d\omega = 0$ (closed)
- 2) $\omega^n \neq 0$ everywhere (ω is non degenerate skew-symmetric)

Examples 1) $(\mathbb{R}^{2n}, \omega_{std})$, $\omega_{std} = \sum_{j=1}^n dx_j \wedge dy_j$
 \uparrow
 $(x_1, y_1, \dots, x_n, y_n)$

2) More generally, $M = T^*X \rightarrow$ smooth mfd

has natural symplectic form ω_{can} :

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in coordinates $\{x_1, \dots, x_n\}$ on X , so

$$T_x^*X = \{ \sum \xi_j (dx_j)_x \} \text{ has coordinates } \{ \xi_j \}$$

$$\omega_{can} = \sum dx_j \wedge d\xi_j \text{ (well-defined!)}$$

3) Σ surface, ω volume form $\Rightarrow (\Sigma, \omega)$ symplectic.

4) S^{2n} does not have a symplectic structure ω

if $n > 1$, because $[\omega]^n$ has to be $\neq 0$.

5) $\mathbb{C}P^n$ has a natural symplectic structure ω_{FS} ;

(can write down explicitly)

Darboux's thm locally, $(M, \omega) \cong (\mathbb{R}^{2n}, \omega_{std})$

So no local invariants!

Rule 2) \Rightarrow true pointwise, 1) \Rightarrow integrability.

Recall given $H: \mathbb{R}^{2n} \rightarrow \mathbb{R}$ Hamiltonian, ③

The evolution eqs for $(x_1(t), \dots, y_n(t))$ are

$$\begin{cases} \dot{x}_j(t) = \partial H / \partial y_j \\ \dot{y}_j(t) = -\partial H / \partial x_j \end{cases} \quad \underline{\text{Hamilton's eqs.}}$$

Globally on (M, ω) , ω determines

$$\begin{aligned} TM &\xrightarrow{\sim} T^*M \\ v &\mapsto \omega(v, -) \end{aligned}$$

so $H: M \rightarrow \mathbb{R} \rightsquigarrow dH \in \Omega^1(M)$

$\rightsquigarrow X_H \in \mathcal{P}(TM)$ Hamiltonian v.f.;

$(\iota_{X_H} \omega = dH)$.

Hamilton's eqs are $\underline{\dot{X}}(t) = X_H(x(t))$,

so we are evolving along the flow $\varphi_H(t)$

of X_H .

Key lemma $\varphi_H(t)$ preserves ω .

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Proof Infinitesimally,

$$L_{X_H} \omega = d(L_{X_H} \omega) + L_{X_H}(d\omega) = ddH = 0.$$

Cartan's magic formula □

$\Rightarrow (M, \omega)$ has a lot of symmetries!

Remark In general, a symmetry $\varphi: (M, \omega) \rightarrow$

is called a symplectomorphism, these

form the group $\text{Symp}(M, \omega)$.

The flow of a vector field X preserves

ω if $L_X \omega$ is closed; X is Hamiltonian

if $L_X \omega$ is exact ($= dH$).

Can also do time dependent vector fields!

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Let's discuss the geometric interpretation

of Noether's principle (symmetry \leftrightarrow conserved quantity).

Consider an action of G

Lie group on (M, ω) , i.e. $\rho: G \rightarrow \text{Symp}(M, \omega)$.

homomorphism. Let's assume:

(*) The differential at id_G has image in

$$\rho_*: \mathfrak{g} \rightarrow \text{HamVect}(M, \omega) \subseteq \Gamma(TM)$$

$\Rightarrow \forall \gamma \in \mathfrak{g}, \rho_*(\gamma) = X_{H_\gamma}$ for some $H_\gamma \in C^\infty(M)$,
(well defined up to constant)

\Rightarrow we obtain map $\mathfrak{g} \rightarrow C^\infty(M)$ linear;

dually, $\mu: M \rightarrow \mathfrak{g}^*$ s.t.

$$\langle \mu(x), \gamma \rangle = H_\gamma(x).$$

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(**) $\mu: M \rightarrow \mathfrak{g}^*$ is G -equivariant.

Def If these hold, we say $G \curvearrowright (M, \omega)$ is Hamiltonian action, and

$\mu: M \rightarrow \mathfrak{g}^*$ is moment map.

Rule Here's general conditions to prove $G \curvearrowright (M, \omega)$ is Hamiltonian, we'll check it by hand in interesting cases.

Ex 1 $M = T^*\mathbb{R}^3 = (\mathbb{R}^6, \omega_{std})$

If $G = \mathbb{R}^3 \curvearrowright M$ action induced by translations

$\mathbb{R}^3 \curvearrowright \mathbb{R}^3$, then the moment map is

$\mu(\underline{x}, \underline{y}) = \underline{y} \in \mathfrak{g}(\mathbb{R}^3)^* \cong \mathbb{R}^3$. This is the

usual momentum!

Let $G = \text{SO}(3) \cong M$ rotations on \mathbb{R}^3 ②

$$\mu(\underline{x}, \underline{y}) = \underline{x} \times \underline{y} \in \text{SO}(3)^{\vee} \cong \mathbb{R}^3 \text{ (algebra notation)}$$

Here we use the identification of

$$\text{Lie algebras } (\mathbb{R}^3, \times) \xrightarrow{\sim} (\text{SO}(3), [\cdot, \cdot])$$

$$\underline{a} = (a_1, a_2, a_3) \mapsto \begin{bmatrix} 0 & -a_3 & a_2 \\ a_3 & 0 & -a_1 \\ -a_2 & a_1 & 0 \end{bmatrix}.$$

plus $\text{SO}(3) \cong \text{SO}(3)^{\vee}$ ($\text{SO}(3)$ -equivariantly)

Then $\rho: \text{SO}(3) \rightarrow \text{Symp}(T^*\mathbb{R}^3, \omega_{\text{can}})$ has

$$d\rho(\underline{a})(\underline{x}, \underline{y}) = (\underline{a} \times \underline{x}, \underline{a} \times \underline{y}).$$

↳ vector field on $T^*\mathbb{R}^3$

This is the Hamiltonian vector field of

$$\begin{aligned} H_{\underline{a}}: T^*\mathbb{R}^3 &\rightarrow \mathbb{R} \quad (\underline{x}, \underline{y}) \mapsto (\underline{x} \times \underline{y}) \cdot \underline{a} = \\ &= \underbrace{\langle \underline{x} \times \underline{y}, \underline{a} \rangle}_{\mu} \end{aligned}$$

Ex 2 $U(n) \simeq \mathbb{C}^n \equiv \mathbb{R}^{2n}$

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(here $\omega_{std} \equiv \frac{i}{2} \sum_{j=1}^n dz_j \wedge d\bar{z}_j$)

Then $\mu: \mathbb{C}^n \rightarrow U(n)^* \cong U(n) \quad \rightarrow$ use inner product $T_{\mathbb{R}}(\mathbb{A}^n)^*$

$\underline{z} \mapsto -\frac{i}{2} \underline{z} \underline{z}^*$

Ex 3 For $U(1) \simeq \mathbb{C}^1$ the moment map is

$\mu(\underline{z}) = -\frac{i}{2} |\underline{z}|^2 \in i\mathbb{R} = U(1)^*$

\rightarrow will be important for us!

Remark $\mu + c$ is also moment map $c \in i\mathbb{R}!$

Marston-Weinstein (1974) quotients of

symplectic mfd by $G \curvearrowright M$ Hamiltonian. Assine.

o) $c \in \mathfrak{g}^*$ is G -invariant & regular

value of μ

$\Rightarrow \mu^{-1}(c) \subseteq M$ smooth mfd with $G \curvearrowright \mu^{-1}(c)$.

$\Rightarrow G \curvearrowright \mu^{-1}(c)$ freely, so $\mu^{-1}(c)/G$ (9)

is smooth manifold (of $\dim M - 2\dim G$).

Then $\mu^{-1}(c)/G$ ($=: X/G$) admits
a natural symplectic form induced by ω
(it's called symplectic quotient)

Ex $U(1) \curvearrowright \mathbb{C}^n$, pick $c \neq 0$ in $i\mathbb{R}$.

$\Rightarrow \mu^{-1}(c)/U(1)$ is either \emptyset , or $\mathbb{C}P^{n-1}$

(with a scaled version of ω_{FS} !).

Key symplectic linear algebra observation:

(V, ω) symplectic v.s. $(\cong (\mathbb{R}^{2n}, \omega_{std}))$

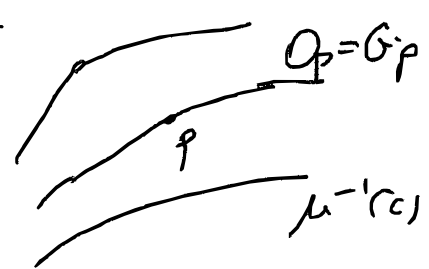
$I \subseteq V$ isotropic i.e. $\omega|_I \equiv 0$

$(\Rightarrow I^\perp \supseteq I)$

Then ω induces natural symplectic (\mathbb{D})
 form Ω on I^\perp/I by $\Omega([v],[w]) = \omega(v,w)$.

The theorem follows by checking that

$T_p \mathcal{O}_p$ is isotropic, and
 $T_p \mu^{-1}(c) (= \ker d\mu_p) = T_p \mathcal{O}_p^\perp$



Moment maps & gauge theory key observations
 of Atiyah-Bott (1983) about surfaces.

$E \rightarrow \Sigma$ $\text{rk}_\mathbb{C} = n$ hermitian bundle.
 $\mathcal{A} = \{ \text{hermitian connections} \} = \mathcal{A}_0 + \mathcal{A}'(\mathcal{G}_E)$
 $\rightarrow U(n)$ -bundle.

is naturally an $(n-1)$ -dimensional
 symplectic manifold.

$$T_A A = \Omega'(g_E), \quad \text{and} \quad \textcircled{11}$$

$$\omega(a, b) := \int_{\Sigma} \text{Tr}(a \wedge b) \quad (\text{constant} \Rightarrow \text{closed})$$

$$\Sigma \Omega^2(M).$$

Now $\xi = \text{gauge prop} \curvearrowright A$ via

$$v \cdot A = A - (d_A v) v^{-1}.$$

$\text{Lie}(\xi) = \Omega^0(\mathfrak{g}_E)$, and the differential

is the map $\text{Lie}(\xi) \rightarrow \Gamma(TA)$

$$\phi \mapsto (A \mapsto -d_A \phi \in T_A A = \Omega^0(\mathfrak{g}_E))$$

Lemma the vector field X sending $A \mapsto -d_A \phi$

is Hamiltonian for $H: A \rightarrow \mathbb{R}$

$$A \mapsto \int \text{Tr}(F_A \wedge \phi)$$

Proof $F_{A+t\alpha} = F_A + t d_A \alpha + O(t^2)$

$$\Rightarrow dH_A(a) = \int \text{Tr}(d_A a \wedge \phi)$$

$$\begin{aligned} \text{Now } \omega_A(X, a) &= \int \text{Tr}(-d_A \phi \wedge a) \quad (\text{by def}) \\ &= \int \text{Tr}(\phi \wedge d_A a) \quad (\text{by Stokes}) \quad \square \end{aligned}$$

Using identification $\Omega^p(\mathfrak{g}_E)^* \cong \Omega^2(\mathfrak{g}_E)$,

and gauge invariance properties of \mathbb{F}_A , we have

Thm The action $\int \mathbb{F}_A$ is Hamiltonian

with moment map

$$A \rightarrow \Omega^2(\mathfrak{g}_E) \quad A \mapsto \mathbb{F}_A$$

In particular, one expects spaces of

Solutions mod gauge to be symplectic

manifolds in good circumstances!

Remark this is all fund!