

27 Sep 2016

Using change of coords to find a matrix

find A so

$$A \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$A \begin{bmatrix} 1 \\ 2 \end{bmatrix} = -1 \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

⊗ "Reversing the check"

check:

$$A \begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ -2 & -2 \end{bmatrix}$$

$$A = \begin{bmatrix} 2 & -1 \\ -2 & -2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix}^{-1}$$

$$\begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 1 & 1 \end{bmatrix} / 3 = \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} / 3$$

$$A = \begin{bmatrix} 2 & -1 \\ -2 & -2 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 1 & 1 \end{bmatrix} / 3 = \begin{bmatrix} 3 & -3 \\ -6 & 0 \end{bmatrix} / 3 = \begin{bmatrix} 1 & -1 \\ -2 & 0 \end{bmatrix}$$

$$\begin{bmatrix} a & c \\ b & d \end{bmatrix}^{-1} = \begin{bmatrix} d & -c \\ -b & a \end{bmatrix} / (ad - bc)$$

⊗ $S = \{e_1, e_2\}$ standard coords $V = \{v_1, v_2\}$ new coords

$$\begin{bmatrix} a \\ b \end{bmatrix}_S = ae_1 + be_2 = a \begin{bmatrix} 1 \\ 0 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

standard coords implied

$$\begin{bmatrix} a \\ b \end{bmatrix}_V = av_1 + bv_2 = a \begin{bmatrix} 1 \\ -1 \end{bmatrix} + b \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

we now mark which coords we're using, so we can switch

$$v = \begin{cases} v_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}_S = \begin{bmatrix} 1 \\ 0 \end{bmatrix}_V \\ v_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}_S = \begin{bmatrix} 0 \\ 1 \end{bmatrix}_V \end{cases}$$

L is our map
 $L: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$Av_1 = 2v_1 \quad Av_2 = -v_2$$

$$L \begin{bmatrix} 1 & -1 \\ -2 & 0 \end{bmatrix}_{S \leftarrow S} =$$

$$\begin{bmatrix} Id & L \\ -1 & 2 \end{bmatrix}_{S \leftarrow V} \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}_{V \leftarrow V} =$$

$$\begin{bmatrix} Id & L \\ 2 & -1 \end{bmatrix}_{V \leftarrow S} / 3 =$$

⊗ abstract maps
⊗ which coords? out ← in

$$A = \boxed{L} \begin{bmatrix} 2 & -1 \\ -2 & -2 \end{bmatrix} \boxed{\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}}_{V \leftarrow S} / 3$$

We should use L here
 A is L in S-coords
 D is L in V-coords

$$L \begin{bmatrix} 1 \\ -1 \end{bmatrix}_S = 2 \begin{bmatrix} 1 \\ -1 \end{bmatrix}_S$$

$$L \begin{bmatrix} 1 \\ 2 \end{bmatrix}_S = -1 \begin{bmatrix} 1 \\ 2 \end{bmatrix}_S$$

$$L \begin{bmatrix} 1 \\ 0 \end{bmatrix}_V = 2 \begin{bmatrix} 1 \\ 0 \end{bmatrix}_V$$

$$L \begin{bmatrix} 0 \\ 1 \end{bmatrix}_V = -1 \begin{bmatrix} 0 \\ 1 \end{bmatrix}_V$$

oops
not S!

$$\begin{bmatrix} r \\ s \end{bmatrix}_V = rv_1 + sv_2$$

$$L \begin{bmatrix} r \\ s \end{bmatrix} = rL \begin{bmatrix} 1 \\ 0 \end{bmatrix}_V + sL \begin{bmatrix} 0 \\ 1 \end{bmatrix}_V$$

$$= r \begin{bmatrix} 2 \\ 0 \end{bmatrix}_V + s \begin{bmatrix} 0 \\ -1 \end{bmatrix}_V$$

$$= \begin{bmatrix} 2r \\ 0 \end{bmatrix} \begin{bmatrix} r \\ s \end{bmatrix} = \begin{bmatrix} 2r \\ -s \end{bmatrix}$$

This showed us the change of coord was same as check.

effect on	A	e^{At}	I	=	J	+	K	$2J-K = A$
$v_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$	2	e^{2t}	1		1		0	2
$v_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$	-1	e^{-t}	1		0		1	-1
in V coords	$\begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix}$		$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$	$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$	$\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$	$\begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix}$		
	(2, -1)		(1, 1)	(1, 0)	(0, 1)		(2, -1)	

$$J \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \quad J \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$J \begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ -1 & 0 \end{bmatrix}$$

$$J = \begin{bmatrix} 1 & 0 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 1 & 1 \end{bmatrix} / 3 = \begin{bmatrix} 2 & -1 \\ -2 & 1 \end{bmatrix} / 3$$

$$J: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

rank 1 matrix

$$\begin{array}{c|cc} * & 2 & -1 \\ \hline 1 & & 2 \\ -1 & & -2 \end{array} \circlearrowleft$$

$$\begin{bmatrix} 1 \\ -1 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}$$

$\underbrace{2 \times 1}_{2 \times 2} \quad \underbrace{1 \times 2}_{2 \times 2}$

Image of J is all multiples of $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$

$$J \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$J \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \frac{[2 \ 1]}{3} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$J \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \frac{[2 \ 1]}{3} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$K = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix} / 3 = \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix} / 3$$

$$\begin{bmatrix} 2 & -1 \\ -2 & 1 \end{bmatrix} / 3 + \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix} / 3 = \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} / 3 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I \quad \checkmark$$

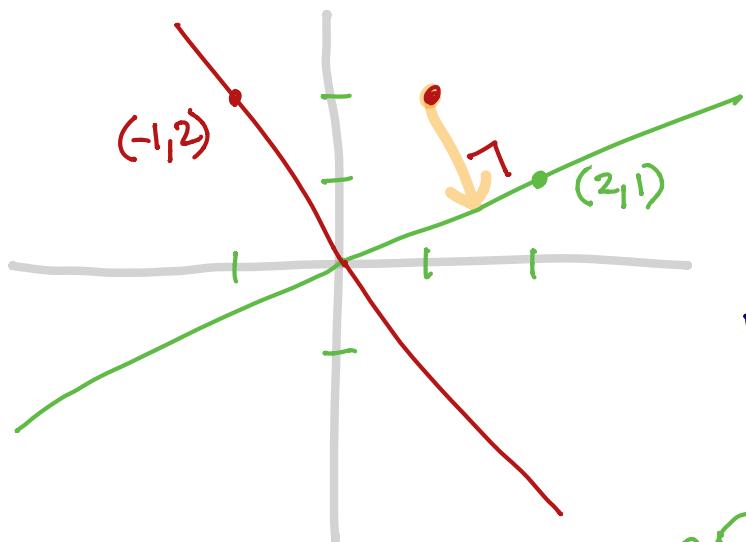
$J \quad K$

$$\begin{bmatrix} 1 & -1 \\ -2 & 0 \end{bmatrix} A = 2 \begin{bmatrix} 2 & -1 \\ -2 & 1 \end{bmatrix} / 3 - 1 \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix} / 3 = \begin{bmatrix} 3 & -3 \\ -6 & 0 \end{bmatrix} / 3 \quad \checkmark$$

$A \quad J \quad K$

$$e^{At} = e^{2t} J + e^{-t} K$$

$$A = 2 J + (-1) K$$



find B so B projects \perp onto this line

$$B \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix} \quad Bv_1 = v_1$$

$$B \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad Bv_2 = 0v_2$$

$$B = \begin{bmatrix} 2 \\ 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \end{bmatrix} / 5 = \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} / 5$$

$A = rJ + sK$

$$\begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} / 5 \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 10 \\ 5 \end{bmatrix} / 5 = \begin{bmatrix} 2 \\ 1 \end{bmatrix} \quad \checkmark$$

$$\begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} / 5 \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} / 5 = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \checkmark$$

What it means to be a basis.

W vector space can add two vectors
multiply by scalars
rules work as expected
vectors in W:

$V = \{v_1, v_2, \dots, v_n\}$ is a basis for W

\Leftrightarrow every $w \in W$ can be written

$$w = r_1 v_1 + r_2 v_2 + \dots + r_n v_n \text{ in exactly one way}$$

$$\Leftrightarrow \text{can write any } w = \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_n \end{bmatrix}_V$$

$\Leftrightarrow \mathbb{R}^n \rightarrow W$ is a bijection 1:1 onto

$$\begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_n \end{bmatrix} \mapsto r_1 v_1 + r_2 v_2 + \dots + r_n v_n$$

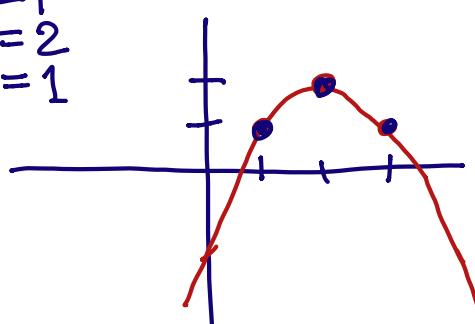
example: all ^{real} polynomials in x of degree ≤ 2

$$\mathbb{R}^3 \cong W = \{a + bx + cx^2\} \text{ for all } a, b, c \in \mathbb{R}$$

$$V = \left\{ \begin{array}{l} v_1 = 1 \\ v_2 = x \\ v_3 = x^2 \end{array} \right. \quad \begin{array}{l} \mathbb{R}^3 \rightarrow W \\ \begin{bmatrix} a \\ b \\ c \end{bmatrix} \mapsto a + bx + cx^2 \end{array}$$

Find $f(x)$ of degree ≤ 2 so

$$\begin{aligned} f(1) &= 1 \\ f(2) &= 2 \\ f(3) &= 1 \end{aligned}$$



$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

we can solve
for a, b, c

$$\left[\begin{array}{ccc|c} 1 & 1 & 1 & 1 \\ 1 & 2 & 4 & 2 \\ 1 & 3 & 9 & 1 \end{array} \right] \xrightarrow{\text{②} \leftarrow \text{②} - \text{①}} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 1 \\ 0 & 1 & 3 & 0 \\ 1 & 3 & 9 & 1 \end{array} \right] \xrightarrow{\text{③} \leftarrow \text{③} - \text{①}} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 1 \\ 0 & 1 & 3 & 0 \\ 0 & 2 & 8 & 0 \end{array} \right]$$

$$\xrightarrow{\text{③} \leftarrow \frac{1}{2}\text{③}} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 1 \\ 0 & 1 & 3 & 0 \\ 0 & 0 & 1 & -1 \end{array} \right] \xrightarrow{\text{①} \leftarrow \text{①} - \text{③}} \left[\begin{array}{ccc|c} 1 & 1 & 0 & 2 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & -1 \end{array} \right]$$

$$f(x) = -2 + 4x - x^2$$

$$f(1) = -2 + 4 - 1 = 1 \quad \textcircled{1}$$

$$f(2) = -2 + 8 - 4 = 2 \quad \textcircled{2}$$

$$f(3) = -2 + 12 - 9 = 1 \quad \textcircled{3}$$

$$\xrightarrow{\text{①} \leftarrow \text{①} - \text{②}} \left[\begin{array}{ccc|c} 1 & 0 & 0 & -2 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & -1 \end{array} \right] \quad \begin{matrix} a = -2 \\ b = 4 \\ c = -1 \end{matrix}$$

basis: \square every w can be written at least one way
 \Leftrightarrow basis spans W

\square every w can be written at most one way
 \Leftrightarrow basis is linearly independent

$\underline{\square}$ every w can be written exactly one way

spans

we can write any $w \in W$

as $w = r_1v_1 + \dots + r_nv_n$ somehow

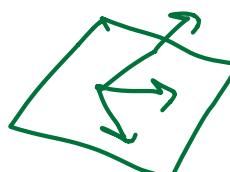
$$w = \begin{bmatrix} r_1 \\ \vdots \\ r_n \end{bmatrix}_V \quad \text{at least one way}$$

example in \mathbb{R}^3

$$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

spans \mathbb{R}^3

$$r \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - r \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} r \\ 0 \\ -r \end{bmatrix}$$



third vector sticks out of plane

second example in \mathbb{R}^3

don't span \mathbb{R}^3

$$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$



third vector in plane of first two

linearly dependent

$$r_1v_1 + r_2v_2 + \dots + r_nv_n = 0 \quad \text{not all } r_i = 0$$

$$0v_1 + 0v_2 + \dots + 0v_n = 0$$

two ways to write zero

$$\begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}_V = \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_n \end{bmatrix}_V$$

two ways to write zero
⇒ we've got a problem

$$\mathbb{R}^n \rightarrow W$$

v_1, v_2, \dots, v_n



if collapsing, seen at origin

$$+ \left\{ w = r_1v_1 + r_2v_2 + \dots + r_nv_n \right\}$$
$$- \left\{ w = s_1v_1 + s_2v_2 + \dots + s_nv_n \right\}$$

and $r_1 \neq s_1$

subtract $0 = (r_1 - s_1)v_1 + (r_2 - s_2)v_2 + \dots + (r_n - s_n)v_n$

$\underbrace{\quad}_{\text{not zero.}}$