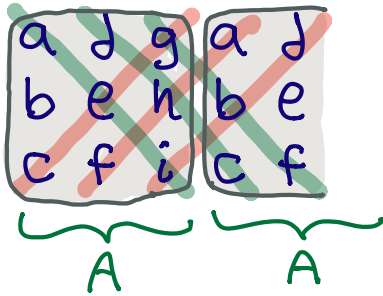


Oct 20, 2016

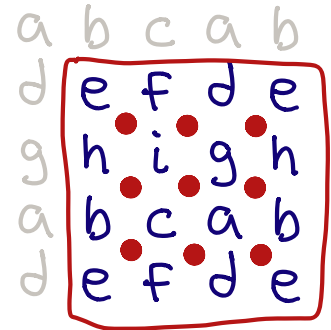
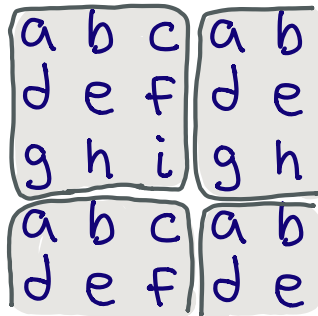
Fast way to compute 3x3 inverses

$$\begin{bmatrix} a & d & g \\ b & e & h \\ c & f & i \end{bmatrix}^{-1} = \frac{\begin{bmatrix} ei-fh & -di+fg & dh-eg \\ -bi+ch & ai-cg & -ah+bg \\ bf-ce & -af+cd & ae-bd \end{bmatrix}}{\det(A)}$$

recall 3x3 determinant:



Do the same thing in both directions, after transposing:



$$\begin{vmatrix} e & f \\ h & i \end{vmatrix} \begin{matrix} d & e \\ b & c \\ a & b \end{matrix} = ei-fh$$

$$e \begin{vmatrix} f & d \\ i & g \end{vmatrix} \begin{matrix} h \\ b & c \\ a & b \end{matrix} = -di+fg$$

$$e \begin{vmatrix} f & d \\ i & g \end{vmatrix} \begin{matrix} h \\ b & c \\ a & b \end{matrix} = dh-eg$$

$$\begin{vmatrix} h & i \\ b & c \end{vmatrix} \begin{matrix} e f d e \\ g h \\ a b \end{matrix} = -bi+ch$$

$$h \begin{vmatrix} i & g \\ c & a \end{vmatrix} \begin{matrix} e f d e \\ b \\ c & a \end{matrix} = ai-cg$$

$$h \begin{vmatrix} i & g \\ c & a \end{vmatrix} \begin{matrix} e f d e \\ b \\ c & a \end{matrix} = -ah+bg$$

$$\begin{vmatrix} b & c \\ e & f \end{vmatrix} \begin{matrix} e f d e \\ h i g h \\ a b \end{matrix} = bf-ce$$

$$b \begin{vmatrix} c & a \\ f & d \end{vmatrix} \begin{matrix} e f d e \\ h i g h \\ a b \end{matrix} = -af+cd$$

$$b \begin{vmatrix} c & a \\ f & d \end{vmatrix} \begin{matrix} e f d e \\ h i g h \\ a b \end{matrix} = ae-bd$$

$$\underbrace{\begin{bmatrix} 2 & 1 & 0 \\ -1 & 2 & 1 \\ 0 & -1 & 0 \end{bmatrix}}_A \underbrace{\begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & -2 \\ 1 & 2 & 5 \end{bmatrix}}_{A^{-1}} / 2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & -1 & 0 & 2 & -1 \\ 1 & 2 & -1 & 1 & 2 \\ 0 & 1 & 0 & 0 & 1 \\ 2 & -1 & 0 & 2 & -1 \\ 1 & 2 & -1 & 1 & 2 \end{bmatrix}$$

$$\begin{matrix} e & f & d & e \\ \begin{vmatrix} h & i \\ b & c \end{vmatrix} & g & h \\ e & f & d & e \end{matrix} = \begin{matrix} a & d & g \\ b & e & h \\ c & f & i \end{matrix}$$

"torus" view

$$\begin{bmatrix} + & - & + \\ - & + & - \\ + & - & + \end{bmatrix}$$

order swapped but sign is -

Orthogonal projection onto plane $x+y+z=0$ in $\mathbb{R}^3$
 $\vec{n} = (1, 1, 1) \mapsto 0$

$$\begin{bmatrix} A \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 1 \\ 0 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 0 \end{bmatrix}$$

$v_1 \ v_2 \ v_3$

$$\begin{aligned} Av_1 &= v_1 \\ Av_2 &= v_2 \\ Av_3 &= 0 \end{aligned}$$

$$S = \{e_1, e_2, e_3\}$$

$$V = \{v_1, v_2, v_3\}$$

$$\begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix} / 3 = \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 1 \\ 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 2 & -1 & -1 \\ 1 & 1 & -2 \\ 1 & 1 & 1 \end{bmatrix} / 3$$

$S \leftarrow S$ A $S \leftarrow V$ C $V \leftarrow V$ D $V \leftarrow S$ C^{-1}

$$= 1 \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \begin{bmatrix} 2 & -1 & -1 \end{bmatrix} / 3 + 1 \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} \begin{bmatrix} 1 & 1 & -2 \end{bmatrix} / 3$$

$$A = \frac{1}{3} \begin{bmatrix} 2 & -1 & -1 \\ -2 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} + \frac{1}{3} \begin{bmatrix} 0 & 0 & 0 \\ 1 & 1 & -2 \\ -1 & -1 & 2 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix}$$

check:

$$A = \frac{1}{3} \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix} - \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix}$$

$\mathbb{I}$
 $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} / 3$
 orthogonal projection onto $(1,1,1)$

check:

$$\frac{1}{3} \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix} \frac{1}{3} \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 1 \\ 0 & -1 & 1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 3 & 0 & 0 \\ -3 & 3 & 0 \\ 0 & -3 & 0 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 0 \end{bmatrix}$$

$v_1 \ v_2 \ v_3$
 $v_1 \ v_2 \ 0$

$$\frac{1}{3} \begin{bmatrix} 2 & -1 & -1 \\ 1 & 1 & -2 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 1 \\ 0 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & -1 & -1 \end{bmatrix} \frac{1}{3} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} = 1 \quad \begin{bmatrix} 2 & -1 & -1 \end{bmatrix} \frac{1}{3} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} = 0 \quad \begin{bmatrix} 2 & -1 & -1 \end{bmatrix} \frac{1}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 0$$

projection $\frac{1}{3} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \begin{bmatrix} 2 & -1 & -1 \end{bmatrix}$ preserves $\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$, zeros $\begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

Determinant from a recurrence relation

$$\begin{array}{c}
 n=0 \quad 1 \quad 2 \quad 3 \quad 4 \\
 \begin{bmatrix} 1 \end{bmatrix} \quad \begin{bmatrix} 1 \end{bmatrix} \quad \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & 1 & 0 \\ -1 & 1 & 1 \\ 0 & -1 & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & 1 & 0 & 0 \\ -1 & 1 & 1 & 0 \\ 0 & -1 & 1 & 1 \\ 0 & 0 & -1 & 1 \end{bmatrix} \\
 \det=1 \quad 1 \quad 2 \quad 3 \quad 5
 \end{array}$$

Expand by minors 1st col

$$\begin{array}{|c|c|c|c|} \hline + & - & + & - \\ \hline - & + & - & + \\ \hline + & - & + & - \\ \hline - & + & - & + \\ \hline \end{array}
 \begin{vmatrix} 1 & 1 & 0 & 0 \\ -1 & 1 & 1 & 0 \\ 0 & -1 & 1 & 1 \\ 0 & 0 & -1 & 1 \end{vmatrix}
 = 1 \begin{vmatrix} 1 & 1 & 0 \\ -1 & 1 & 1 \\ 0 & -1 & 1 \end{vmatrix} - (-1) \begin{vmatrix} 1 & 0 & 0 \\ -1 & 1 & 1 \\ 0 & -1 & 1 \end{vmatrix}$$

$$\begin{array}{l}
 f(0)=1 \\
 f(1)=1
 \end{array}$$

$$f(4) = f(3) + f(2)$$

$$f(n) = f(n-1) + f(n-2)$$

n	f(n)
0	1
1	1
2	2
3	3
4	5
5	8



$f(5)$ = Paths of length 5, $\odot x$ to $\odot x$

$$f(0)=1$$

0

$$f(5)=8$$

$$f(1)=1$$

1

$$f(2)=2$$

1 1

$f(1)$

2

$f(0)$

$$f(3)=3$$

1 1 1

$f(2)$

1 2

2 1

$f(1)$

$$f(4)=5$$

1 1 1 1

$f(3)$

1 2

2 1

2 1 1

$f(2)$

2 2

1

1

1

1

1

1

1

1

1

1

1

1

1

1

1

1

1 1 1 1

1 1 2

1 2 1

2 1 1

2 2

2 2

2 2

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2 2

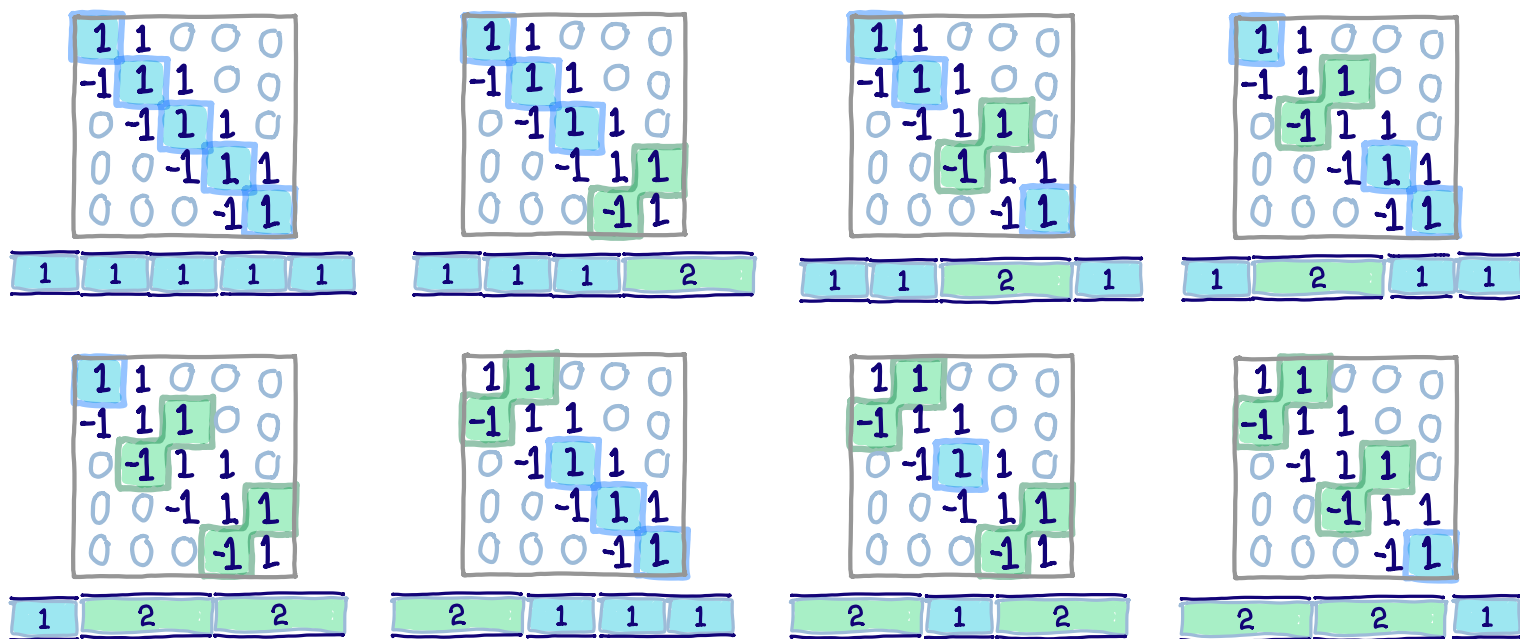
2 2

2 2

2 2

$f(4)$

$f(3)$



8 of the 120 terms of this determinant are 1. The rest are zero.

$$f(n) = a f(n-1) + b f(n-2)$$

Guess that the recurrence is of this form. Find a, b .

n	$f(n) = a f(n-1) + b f(n-2)$
2	$2 = 1a + 1b$
3	$3 = 2a + 1b$
4	$5 = 3a + 2b$

$$\begin{bmatrix} 1 & 1 & | & 2 \\ 2 & 1 & | & 3 \\ 3 & 2 & | & 5 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 & | & 2 \\ 0 & -1 & | & -1 \\ 0 & -1 & | & -1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & | & 1 \\ 0 & 1 & | & 1 \\ 0 & 0 & | & 0 \end{bmatrix} \quad a=b=1$$

$$\begin{bmatrix} f(1) \\ f(2) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} f(0) \\ f(1) \end{bmatrix}$$

$$\begin{bmatrix} f(2) \\ f(3) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} f(1) \\ f(2) \end{bmatrix}$$

$$\begin{bmatrix} f(n) \\ f(n+1) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}^n \begin{bmatrix} f(0) \\ f(1) \end{bmatrix}$$

Formula for n^{th} power of matrix gives formula for $f(n)$.

Eigenvalues will give us this formula.

Cramer's rule

$$\begin{bmatrix} a & d & g \\ b & e & h \\ c & f & i \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} r \\ s \\ t \end{bmatrix}$$

$$x = \frac{\begin{vmatrix} r & d & g \\ s & e & h \\ t & f & i \end{vmatrix}}{\begin{vmatrix} a & d & g \\ b & e & h \\ c & f & i \end{vmatrix}}$$

$$y = \frac{\begin{vmatrix} a & r & g \\ b & s & h \\ c & t & i \end{vmatrix}}{\begin{vmatrix} a & d & g \\ b & e & h \\ c & f & i \end{vmatrix}}$$

$$z = \frac{\begin{vmatrix} a & d & r \\ b & e & s \\ c & f & t \end{vmatrix}}{\begin{vmatrix} a & d & g \\ b & e & h \\ c & f & i \end{vmatrix}}$$

why?

$$\begin{bmatrix} r \\ s \\ t \end{bmatrix} = \begin{bmatrix} a \\ b \\ c \end{bmatrix} x + \begin{bmatrix} d \\ e \\ f \end{bmatrix} y + \begin{bmatrix} g \\ h \\ i \end{bmatrix} z$$

Use linearity

$$\begin{vmatrix} r & d & g \\ s & e & h \\ t & f & i \end{vmatrix} = \begin{vmatrix} a & d & g \\ b & e & h \\ c & f & i \end{vmatrix} x + \begin{vmatrix} d & e & h \\ e & f & i \\ f & i & i \end{vmatrix} y + \begin{vmatrix} d & e & h \\ f & i & i \end{vmatrix} z$$

$$= x \begin{vmatrix} a & d & g \\ b & e & h \\ c & f & i \end{vmatrix} + y \begin{vmatrix} d & d & g \\ e & e & h \\ f & f & i \end{vmatrix} + z \begin{vmatrix} g & d & g \\ h & e & h \\ i & f & i \end{vmatrix}$$