

Lecture 10

Plan for the next few lectures: deeper study of linear transformations

- Change of basis
- Eigenvalues, eigenvectors, diagonalization

Today: determinants

Discussion / opinion: the determinant (as we will see shortly) is a number associated to a linear transformation.

it is not a very useful computational tool, but it has an important theoretical value.

Usually, it is introduced earlier. In fact, determinants predate linear algebra!

We introduce them today because:

- They become necessary in what follows
- They are relatively light in complexity

So what is the determinant?

- 1×1 matrices

The determinant of a 1×1 matrix (a) is a . Boring.

- 2×2 matrices

The determinant of the matrix $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ is $ad - bc$.

Let's see some examples:

Example 1 • $A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \Rightarrow \det(A) = 1 \cdot 1 - 0 \cdot 0 = 1$

• $A = \begin{pmatrix} 3 & 0 \\ 0 & 1 \end{pmatrix} \Rightarrow \det(A) = 3 \cdot 1 - 0 \cdot 0 = 3$

• $A = \begin{pmatrix} 5 & 0 \\ 0 & 7 \end{pmatrix} \Rightarrow \det(A) = 5 \cdot 7 - 0 \cdot 0 = 35$

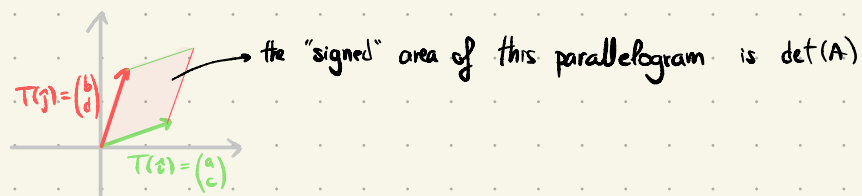
- $A = \begin{pmatrix} 5 & 9 \\ 0 & 7 \end{pmatrix} \Rightarrow \det(A) = 5 \cdot 7 - 9 \cdot 0 = 35$

- $A = \begin{pmatrix} a & b \\ 0 & d \end{pmatrix} \Rightarrow \det(A) = ad$

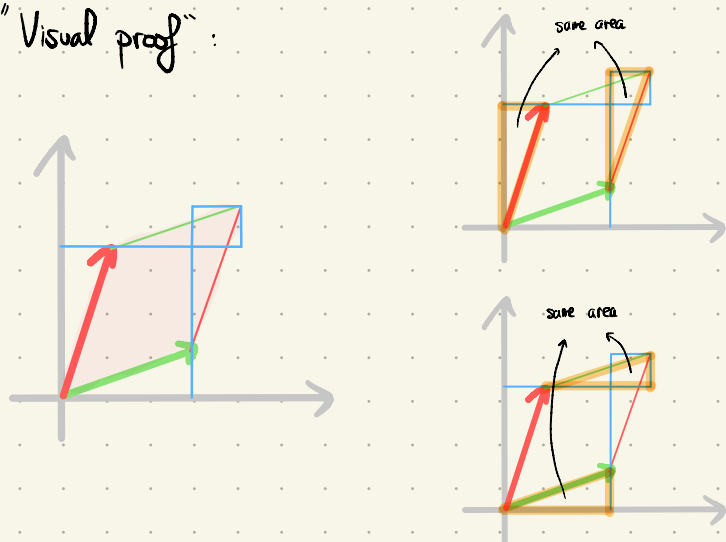
- $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \Rightarrow \det(A) = -1$

The idea: let's picture the matrix A as usual:

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}$$



"Visual proof":

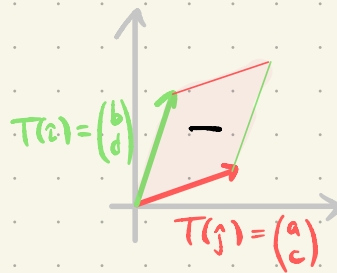
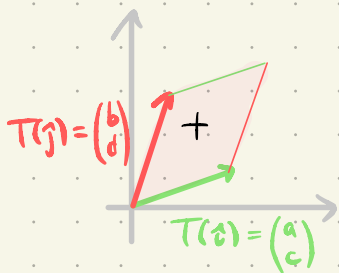


However this double counts $\text{Area}(\square)$ and includes the areas of \triangle and \triangle .

Therefore

$$\text{Area} \left(\begin{array}{c} c \\ d \\ \hline a \quad b \end{array} \right) = \text{Area} \left(\begin{array}{c} \square \\ \hline ad \end{array} \right) - \text{Area} \left(\begin{array}{c} \square \\ \hline bc \end{array} \right)$$

It is "signed" in the sense that



Reversing "orientation" changes the sign.

Important observation: A is invertible $\Leftrightarrow T(\hat{i})$ and $T(\hat{j})$ are l.i.

$\Leftrightarrow T(\hat{i})$ and $T(\hat{j})$ are not on the same line
2x2 matrices only!

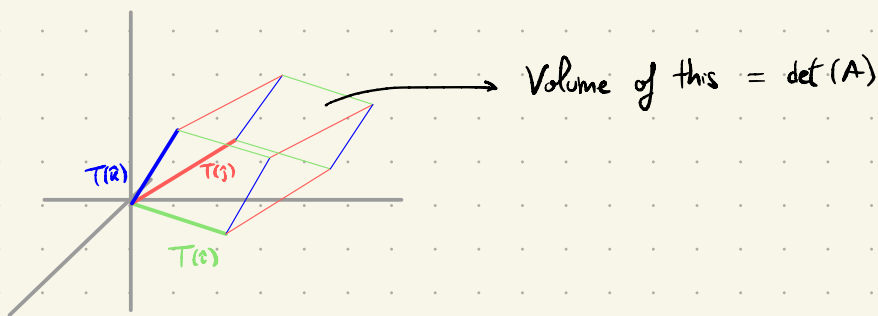
\Leftrightarrow The signed area of the parallelogram is $\neq 0$.

$\Leftrightarrow \det(A) \neq 0$.

This pattern holds in general, for square matrices.

In general, the determinant will be the "volume of the signed parallelepiped" formed by the vectors

$T\left(\begin{pmatrix} 1 \\ 0 \\ \vdots \end{pmatrix}\right), \dots, T\left(\begin{pmatrix} 0 \\ \vdots \\ 1 \end{pmatrix}\right)$.



Observe: $T(\hat{i}), T(\hat{j}), T(\hat{k})$ are l.i. \Leftrightarrow they lie on the same plane

\Leftrightarrow volume of the parallelepiped = 0

$\Leftrightarrow \det(A) = 0$.

How to compute the determinant for a general square matrix?

Definition 1: Let A be a square matrix, and put it into rref. Let $s = \# \text{swaps}$ and K_1, \dots, K_t the scalars that were used to divide the rows. Then, $\det(A) = \begin{cases} 0 & \text{if some row has no pivot} \\ (-1)^s K_1 \dots K_t & \text{otherwise} \end{cases}$

Remark: Clearly A is invertible $\Leftrightarrow \det(A) \neq 0$.

Remark: It suffices to do rref until putting A into triangular form: $\begin{pmatrix} 1 & & * \\ & \ddots & \\ 0 & & 1 \end{pmatrix}$
(since no swaps or scalings will be performed after that point)

Example 2: • If $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ is invertible and $a \neq 0$ then

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \xrightarrow{I \rightarrow \frac{1}{a}I} \begin{pmatrix} 1 & \frac{b}{a} \\ c & d \end{pmatrix} \xrightarrow{II \rightarrow II - cI} \begin{pmatrix} 1 & \frac{b}{a} \\ 0 & d - \frac{bc}{a} \end{pmatrix} \xrightarrow{II \rightarrow \frac{1}{d - \frac{bc}{a}} II} \begin{pmatrix} 1 & \frac{b}{a} \\ 0 & 1 \end{pmatrix}$$

$\Rightarrow \det(A) = (-1)^0 \cdot a \cdot \left(d - \frac{bc}{a}\right) = ad - bc$

• If $a = 0$ then

$$\begin{pmatrix} 0 & b \\ c & d \end{pmatrix} \xrightarrow{\frac{1}{c} \cdot II} \begin{pmatrix} 0 & b \\ 1 & \frac{d}{c} \end{pmatrix} \xrightarrow{I \leftrightarrow II} \begin{pmatrix} 1 & \frac{d}{c} \\ 0 & b \end{pmatrix} \xrightarrow{I \rightarrow \frac{1}{b}I} \begin{pmatrix} 1 & \frac{d}{c} \\ 0 & 1 \end{pmatrix}$$

$\det(A) = (-1)^1 \cdot c \cdot b = -bc = ad - bc$

Example 3: $A = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 3 \\ -1 & 2 & 1 \end{pmatrix} \xrightarrow{III \rightarrow III + I} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 3 \\ 0 & 2 & 0 \end{pmatrix} \xrightarrow{III \rightarrow III - 2II} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 3 \\ 0 & 0 & -6 \end{pmatrix} \xrightarrow{III \rightarrow \frac{1}{-6} III} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{pmatrix}$

So $\det(A) = (-1)^0 \cdot (-6) = 6$

Properties of the determinant.

Theorem 1: Let A and B be square $n \times n$ matrices. Then $\det(AB) = \det(A) \det(B)$.

Proof:

• If A is not invertible, $\text{Im}(A) \neq \mathbb{R}^n$, hence $\text{Im}(AB) \neq \mathbb{R}^n$, so AB is not invertible. Thus

$$\det(AB) = 0 = \det(A) \det(B)$$

• If B is not invertible, $\text{Ker}(B) \neq \{0\}$, hence $\text{Ker}(AB) \neq \{0\}$, so AB is not invertible. Thus

$$\det(AB) = 0 = \det(A) \det(B)$$

- If A, B are both invertible:

Recall that $(A \mid I_n) \xrightarrow{\text{Gauss}} (I_n \mid A^{-1})$

Similarly, $(A \mid C) \rightarrow (I_n \mid A^{-1}C)$ (Extra exercise)

In particular, if $C=AB$,

$$(A \mid AB) \xrightarrow{\text{Gauss}} (I_n \mid B) \rightsquigarrow s, k_2, \dots, k_t \text{ for } A$$

Now keep doing Gaussian elimination on $B \rightsquigarrow s', k'_2, \dots, k'_t$ for B :

$$\left(* \mid I_n \right)$$

Looking at the RHS of the divider, we have put AB into rref, hence

$$\det(AB) = (-1)^{s+s'} k_2 \dots k_t \cdot k'_2 \dots k'_t = (-1)^s k_2 \dots k_t \cdot (-1)^{s'} k'_2 \dots k'_t = \det(A) \cdot \det(B) \quad \square$$

Corollary: For any square matrix A ,

- $\det(A^n) = \det(A)^n$

- $\det(A^{-1}) = \det(A)^{-1}$

Proof: The first one is clear. For the second one: $I_n = AA^{-1} \Rightarrow 1 = \det(A) \cdot \det(A^{-1})$

Remark: Swapping two rows of A changes the determinant to $-\det(A)$.

Alternative approach to compute the determinant.

Theorem 2 (Laplace expansion) Let $A = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{n1} & \dots & a_{nn} \end{pmatrix}$ be an $n \times n$ matrix.

Then $\det(A)$ can be computed recursively as:

$$a_{11} \det \begin{pmatrix} a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & & & \vdots \\ a_{n2} & \dots & & a_{nn} \end{pmatrix} - a_{21} \det \begin{pmatrix} a_{11} & a_{13} & \dots & a_{1n} \\ a_{31} & a_{33} & \dots & a_{3n} \\ \vdots & & & \vdots \\ a_{n1} & a_{n3} & \dots & a_{nn} \end{pmatrix} + \dots + (-1)^{n+1} \det \begin{pmatrix} a_{11} & \dots & a_{1,n-1} \\ \vdots & & \vdots \\ a_{n-1,1} & \dots & a_{n-1,n-1} \end{pmatrix}$$

Proof: omitted.

Example 4: let's find the determinant of $A = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 3 \\ -1 & 2 & 1 \end{pmatrix}$.

$$\det(A) = 1 \cdot \det \begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix} - 0 \cdot \det \begin{pmatrix} 0 & -1 \\ 2 & 1 \end{pmatrix} + (-1) \cdot \det \begin{pmatrix} 0 & -1 \\ 1 & 3 \end{pmatrix} = 1 \cdot (-5) - 0 \cdot 2 - 1 \cdot 1 = -6$$

In fact this can be done along any row or column.

Theorem 2:

Laplace expansion (or cofactor expansion)

We can compute the determinant of an $n \times n$ matrix A by Laplace expansion down any column or along any row.

Expansion down the j th column:

$$\det A = \sum_{i=1}^n (-1)^{i+j} a_{ij} \det(A_{ij}).$$

Expansion along the i th row:

$$\det A = \sum_{j=1}^n (-1)^{i+j} a_{ij} \det(A_{ij}).$$

Definition 2: Let $A = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{pmatrix}$ be an $m \times n$ matrix. Then the transpose of A is

$$A^T = \begin{pmatrix} a_{11} & \dots & a_{m1} \\ \vdots & & \vdots \\ a_{1n} & \dots & a_{mn} \end{pmatrix}$$

Theorem 3: Let $A = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{n1} & \dots & a_{nn} \end{pmatrix}$ be a square matrix. Then $\det(A) = \det(A^T)$.

Proof: • Case $n=2$: $\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc = \det \begin{pmatrix} a & c \\ b & d \end{pmatrix} \checkmark$

• Case $n=3$:

$$\det(A) = \det \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} \begin{matrix} \downarrow \\ \text{Laplace, 1st col} \end{matrix} = a_{11} \cdot \det \begin{pmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{pmatrix} - a_{21} \cdot \det \begin{pmatrix} a_{12} & a_{13} \\ a_{32} & a_{33} \end{pmatrix} + a_{31} \cdot \det \begin{pmatrix} a_{12} & a_{13} \\ a_{22} & a_{23} \end{pmatrix}$$

$\begin{matrix} \uparrow & \uparrow & \uparrow \\ = \text{by } n=2 & = \text{by } n=2 & = \text{by } n=2 \end{matrix}$

$$\det(A^T) = \det \begin{pmatrix} a_{11} & a_{21} & a_{31} \\ a_{12} & a_{22} & a_{32} \\ a_{13} & a_{23} & a_{33} \end{pmatrix} \begin{matrix} \downarrow \\ \text{Laplace, 1st row} \end{matrix} = a_{11} \cdot \det \begin{pmatrix} a_{22} & a_{32} \\ a_{23} & a_{33} \end{pmatrix} - a_{21} \cdot \det \begin{pmatrix} a_{21} & a_{31} \\ a_{23} & a_{33} \end{pmatrix} + a_{31} \cdot \det \begin{pmatrix} a_{21} & a_{31} \\ a_{22} & a_{32} \end{pmatrix}$$

The general case is similar. \square

In-class exercises:

1. Compute the determinant of $\begin{pmatrix} 0 & 1 & 2 \\ 1 & 2 & -1 \\ 1 & 1 & 1 \end{pmatrix}$

- Using rref

- Using the Laplace expansion

2. let $A = \begin{pmatrix} 2 & 1 \\ 1 & -1 \end{pmatrix}$. Compute $\det(A^{-3})^T$.

3. Is it true that $\det(A+B) = \det(A) + \det(B)$?