## Mathematics W4061y Differentiable Manifolds

## Practice Final Exam May 12, 2014

Hint: problems may be useful in solving other problems. Manifolds are without boundary unless otherwise stated.

- **1.** Define the *tensor product*  $\phi \otimes \psi \in T^{k+\ell}V$  of two tensors  $\phi \in T^kV$  and  $\psi \in T^\ell V$ .
- **2.** Let  $SL(2) = \{A \in M_{2 \times 2} \mid \det A = 1\}$ . Is it a manifold? Either prove that it is or prove that it isn't. If it is, what is its dimension? Extra credit: same question for SL(n).
- **3.** Recall that the *spherical coordinates*  $(\rho, \phi, \theta)$  of a vector  $\vec{v} \in \mathbf{R}^3$  are determined by the formula

 $(x, y, z) = (\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi).$ 

Here  $\rho$  is the length of  $\vec{v}$ ;  $\phi$  is its angle with the vertical; and  $\theta$  is the angle that its projection onto the horizontal makes with the positive x-axis.

Fix intervals  $(\rho_{-}, \rho_{+}) \subset [0, \infty)$ ,  $(\phi_{-}, \phi_{+}) \subset [0, \pi]$ , and  $(\theta_{-}, \theta_{+}) \subset [0, 2\pi]$ . Let  $S \subset \mathbb{R}^{3}$  be the bounded open set consisting of points  $\vec{v}$  whose spherical coordinates  $(\rho, \phi, \theta)$  lie in these three intervals, respectively. Use the change of variables formula to compute the volume of S, that is,  $\int_{S} 1$ . Hint: the Jacobian determinant simplifies dramatically.

**4.** (a) For  $U \subset \mathbf{R}^n$  open,  $\omega \in \Omega^p(U)$ , and  $\eta \in \Omega^q(U)$ , prove that

$$d(\omega \wedge \eta) = d\omega \wedge \eta + (-1)^p \,\omega \wedge d\eta.$$

(b) If  $\nu \in \Omega^r(U)$  as well, state and prove a similar formula for  $d(\omega \wedge \eta \wedge \nu)$ .

**5.** If  $M \subset \mathbf{R}^m$  and  $N \subset \mathbf{R}^n$  are compact oriented manifolds of dimensions k and  $\ell$  respectively,  $\mu \in \Omega^k(\mathbf{R}^m)$ , and  $\nu \in \Omega^\ell(\mathbf{R}^n)$ , prove that

$$\int_{M \times N} \pi_1^* \mu \wedge \pi_2^* \nu = \int_M \mu \int_N \nu.$$

6. (a) If  $U \subset \mathbf{R}^n$  is open and  $M \subset U$  is a compact oriented manifold of dimension k, prove that the linear functional  $\int_M : H^k(U) \to \mathbf{R}$  is well defined.

(b) If  $M = \partial N$  for some compact oriented N, prove that this functional is zero.

**7.** Suppose  $U \subset \mathbf{R}^3$  is any open set such that whenever  $(x, y, z) \in U$  and  $s, t \in \mathbf{R}$ , then (x, y + s, z + t) is also in U. Compute the de Rham cohomology  $H^2(U)$ .

## CONTINUED OVERLEAF ...

- 8. Suppose M and N are manifolds, and suppose a smooth map  $h: M \to N$  may be expressed as  $h = g \circ f$  for some smooth  $f: M \to \mathbf{R}^k$  and  $g: \mathbf{R}^k \to N$ . Prove that if  $\eta \in \Omega^i(N)$  is closed for i > 0, then  $h^*\eta$  is exact.
- **9.** We proved that there exists  $\eta \in \Omega^n(S^n)$  such that  $\int_{S^n} \eta \neq 0$ . If M is a compact oriented manifold of dimension n > 0 and  $h : M \to S^n$  is smooth but not surjective, prove that  $\int_M h^* \eta = 0$ .
- 10. Say  $\omega, \eta \in \Omega^1(\mathbf{R}^n)$  satisfy  $d\omega = d\eta$ , and C, D are compact connected parametric curves (i.e. 1-dimensional manifolds with boundary) having the same initial and terminal points. Show that

$$\int_C \omega + \int_D \eta = \int_D \omega + \int_C \eta.$$