

Mathematics V1208y
Honors Mathematics IV

Assignment #12

Due April 29, 2016

Reading: Apostol, §§12.14–12.20 (pp. 443–462).

- *1. Let $f : [a, b] \rightarrow \mathbb{R}$ be a differentiable function. Express the subset of \mathbb{R}^3 swept out by the graph of f as it rotates about the horizontal x -axis as a parametric surface in \mathbb{R}^3 : the *surface of revolution*. Write down an expression for the surface area between $x = a$ and $x = b$, as an integral from a to b .
- 2. The *torus* $T \subseteq \mathbb{R}^3$ is the set of all vectors of the form $3\mathbf{x} + \mathbf{y}$, where \mathbf{x} is of unit length and orthogonal to \mathbf{e}_1 , and \mathbf{y} is of unit length and orthogonal to $\mathbf{x} \times \mathbf{e}_1$. Express the torus as a piecewise parametric smooth surface. Integrate your favorite function or vector field.
- *3. Let $r : T \rightarrow S$ be a parametric surface and $\gamma : [a, b] \rightarrow T$ a path in the plane, so that $r \circ \gamma : [a, b] \rightarrow S$ is a path in space. Show that the tangent vector to $r \circ \gamma$ is orthogonal to the outward normal.
- 4. Suppose that a piecewise parametric surface can be expressed *implicitly*, that is, $S = S_1 \cup \cdots \cup S_k$ with S_i parametrized by $r_i : T_i \rightarrow S_i$ can be expressed as

$$S = \{\mathbf{x} \in \mathbb{R}^3 \mid f(\mathbf{x}) = 0\}$$

for a differentiable $f : \mathbb{R}^3 \rightarrow \mathbb{R}$. Show that at each point of S , ∇f is a nonzero scalar multiple of the outward normal $\partial r_i / \partial u \times \partial r_i / \partial v$. (Hint: what is $f \circ r_i$?) Give an example.

- 5. Apostol §12.4 (p. 424) 8, 10.
- 6. Apostol §12.6 (pp. 429–30) 2, *4.
- 7. Apostol §12.10 (pp. 436–8) *5, *6, *7.

Before doing the above problems, see the note on the back of this sheet about Apostol's notation for line and surface integrals.

- 8. Apostol §12.13 (pp. 442–3) *1, 3, *6, *11.

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A NOTE ON APOSTOL'S NOTATION FOR INTEGRALS

Before attempting problems where Apostol gives surface integrals, be sure to read his §12.9 (pp. 434–6), “Other notations for surface integrals.” I have summarized 3 key points below.

(1) **Line integrals.** The LHS and RHS are Apostol's notation and my notation, respectively, for line integrals of vector fields in \mathbb{R}^3 :

$$\int_C P dx + Q dy + R dz = \int_C (P, Q, R) \cdot d\gamma.$$

In some sense we agree, since formally $d\gamma = \gamma'(t) dt = \left(\frac{dx}{dt}, \frac{dy}{dt}, \frac{dz}{dt}\right) dt = (dx, dy, dz)$. Just don't ask what these quantities really are! It's just formal notation. The real definition, as you know, is an integral from a to b with respect to t .

(2) **Surface integrals of scalar fields**, otherwise known as integrals with respect to surface area. Once again, Apostol's notation and my notation are:

$$\iint_S \phi dS = \iint_S \phi \|d\mathbf{r}^2\|.$$

Again, the idea is that formally $dS = \left\| \frac{\partial \mathbf{r}}{\partial u} \times \frac{\partial \mathbf{r}}{\partial v} \right\| du dv$, and the factors of du and dv “cancel”.

(3) **Surface integrals of vector fields.** Here our two notations are

$$\iint_S F \cdot \mathbf{n} dS = \iint_S F \cdot d\mathbf{r}^2.$$

Yet again, formally this sort of makes sense since

$$\mathbf{n} = \frac{\frac{\partial \mathbf{r}}{\partial u} \times \frac{\partial \mathbf{r}}{\partial v}}{\left\| \frac{\partial \mathbf{r}}{\partial u} \times \frac{\partial \mathbf{r}}{\partial v} \right\|}, \quad dS = \left\| \frac{\partial \mathbf{r}}{\partial u} \times \frac{\partial \mathbf{r}}{\partial v} \right\| du dv, \quad d\mathbf{r}^2 = \frac{\partial \mathbf{r}}{\partial u} \times \frac{\partial \mathbf{r}}{\partial v} du dv.$$

When $F = (P, Q, R)$, Apostol sometimes denotes the same surface integral by

$$\iint_S P dy \wedge dz + Q dz \wedge dx + R dx \wedge dy.$$

The formal justification here is that the first component of $d\mathbf{r}^2$ is

$$\left(\frac{\partial y}{\partial u} \frac{\partial z}{\partial v} - \frac{\partial z}{\partial u} \frac{\partial y}{\partial v} \right) du dv = \frac{\partial(y, z)}{\partial(u, v)} du dv,$$

using the notation for the Jacobian determinant introduced on p. 394, and similarly for the other two components.