

Mathematics G4403y
Modern Geometry

Assignment #10

Due March 5, 2014

0. (Optional for extra credit)

(a) Let M be a smooth manifold, $X \in VF(M)$. Show that there exists a positive smooth $f : M \rightarrow \mathbb{R}$ so that the flow of fX is globally defined.

(b) An open $U \subset \mathbb{R}^n$ is *star-shaped* if there exists $\mathbf{p} \in U$ so that for all $\mathbf{q} \in U$, the line segment from \mathbf{p} to \mathbf{q} is contained in U . Prove that any star-shaped set is diffeomorphic to \mathbb{R}^n . Hint: if $X(\mathbf{q}) = \mathbf{q} - \mathbf{p}$, for a suitably chosen f , construct a diffeomorphism taking the flow of fX to the flow of X .

In the remaining problems, M always denotes a Riemannian manifold with its Levi-Civita connection.

1. A subset S of M is (*geodesically*) *convex* if for each $p, q \in S$, there is a minimizing geodesic, unique in M , lying wholly in S . Show that every point p has an open convex neighborhood, as follows.

(a) Let V be a totally normal neighborhood. For ε small enough that $\exp_p B_{3\varepsilon}(0) \subset V$, define $W_\varepsilon = \{(q, v) \in TM \mid d(p, q) < \varepsilon, v \in T_q M, |v| = 1\}$ and let $f : W_\varepsilon \times (-2\varepsilon, 2\varepsilon) \rightarrow \mathbb{R}$ be given by

$$f(q, v, t) = d(\exp_q tv, p)^2.$$

Show that f is smooth. Hint: although d is not smooth in general (even on a circle), you can calculate in normal coordinates centered at p .

(b) Show that for small enough ε , $\partial^2 f / \partial t^2 > 0$ on $W_\varepsilon \times (-2\varepsilon, 2\varepsilon)$. Hint: calculate $f(p, v, t)$ explicitly.

(c) If $q_1, q_2 \in \exp_p B_\varepsilon(0)$ and γ is a minimizing geodesic from q_1 to q_2 , show that $d(\gamma(t), p)$ attains its maximum at one of the endpoints.

(d) Show that $\exp_p B_\varepsilon(0)$ is convex.

2. (a) Show that the intersection of convex sets (in the sense above) is convex.

(b) Use problem **0** to show that an open convex set is diffeomorphic to \mathbb{R}^n .

(c) Prove the result promised last semester: every smooth manifold has a good cover.

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3. (a) Let $\Gamma : [0, 1] \times [0, 1] \rightarrow M$ be a smooth map, and let $\gamma_u(v) = \Gamma(u, v)$. If γ_0 is a geodesic, $\Gamma(u, 0) = p$, and $\Gamma(u, 1) = q$, show that the “first variation” $\frac{d}{du}\ell(\gamma_u)|_{u=0} = 0$.
- (b) Give an example to show that this is false if $\Gamma(u, 0)$ or $\Gamma(u, 1)$ are not constant.
- (c) Now let $\Gamma : [0, 1] \times S^1 \rightarrow M$ be a smooth map, $\gamma_u(v) = \Gamma(u, v)$, such that γ_0 is a (closed) geodesic. Show that $\frac{d}{du}\ell(\gamma_u)|_{u=0} = 0$. Notice that there are no constraints on any $\Gamma(u, v_0)$.
4. Let $M \subset \mathbb{R}^3$ be a surface of revolution, parametrized by $(t, \theta) \mapsto (a(t) \cos \theta, a(t) \sin \theta, b(t))$.
- (a) Compute the metric elements in (t, θ) coordinates.
- (b) Compute the Christoffel symbols in (t, θ) coordinates.
- (c) Show that each *meridian* $\theta = \theta_0$ is a geodesic.
- (d) Give necessary and sufficient conditions for a *latitude* $t = t_0$ to be a geodesic.
5. A *divergent curve* in M is a smooth map $\gamma : [0, \infty) \rightarrow M$ which eventually leaves any compact set $C \subset M$, that is, there exists t_C so that $t > t_C$ implies $\gamma(t) \notin C$. Show that M is complete if and only if all divergent curves have infinite arclength.
6. Show that a homogeneous space $M = G/H$ on which G acts by isometries is complete.
7. Let G be a Lie group equipped with a bi-invariant metric, \mathfrak{g} its Lie algebra of left-invariant vector fields.
- (a) For any $X, Y, Z \in \mathfrak{g}$, show that

$$\langle [X, Y], Z \rangle = -\langle Y, [X, Z] \rangle.$$

Hint: let $\gamma(t)$ be the flow of X from the identity, let $\text{Ad}_g : G \rightarrow G$ be $\text{Ad}_g(h) = ghg^{-1}$, and compute $\frac{d}{dt}\langle \text{Ad}_{\gamma(t)}Y, \text{Ad}_{\gamma(t)}Z \rangle$.

- (b) Show that $\nabla_X Y = \frac{1}{2}[X, Y]$.
- (c) Show that the geodesics through the identity are precisely the one-parameter subgroups, and that arbitrary geodesics are (right or left) translates of one-parameter subgroups.
- (d) Show that $\exp = \text{exp}$, i.e. the Lie and Riemannian exponential maps coincide.
- (e) Show that $SL(2, \mathbb{R})$ cannot admit a bi-invariant metric.