

A class of globally solvable systems of BSDE and applications

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(FORWARD) SDE

The equation:

$$X_0 = x, \quad dX_t = \mu(X_t) dt + \sigma(X_t) dB_t, \quad t \in [0, T].$$

Causality principle(s):

$$X_t = F(t, \{B_s\}_{s \in [0, t]}) \quad \text{(strong)}$$

$$\{X_s\}_{s \in [0, t]} \perp\!\!\!\perp \{B_s - B_t\}_{s \in [t, T]} \quad \text{(weak)}$$

Solution by simulation (Euler scheme):

$$1) X_0 = x, \quad 2) X_{t+\Delta t} \approx X_t + \mu(X_t) \Delta t + \sigma(X_t) \Delta \zeta,$$

where we draw $\Delta \zeta = B_{t+\Delta t} - B_t$ from $N(0, \sqrt{\Delta t})$.

BSDE ARE NOT BACKWARD SDE

The equation:

$$dX_t = \mu(X_t) dt + \sigma(X_t) dB_t, \quad t \in [0, T], \quad X_T = \xi.$$

Backwards solution by simulation:

$$1) X_T = \xi, \quad 2) X_{t-\Delta t} \approx X_t - \mu(X_{t-\Delta t}) \Delta t - \sigma(X_{t-\Delta t})(B_t - B_{t-\Delta t})$$

The solution is **no longer defined**, or, at best, **no longer adapted**:

$$\text{e.g., if } dX_t = dB_t, \quad X_T = 0 \quad \text{then} \quad X_t = B_t - B_T.$$

Fix: to restore adaptivity, make $Z_t = \sigma(X_t)$ a part of the solution

$$dX_t = \mu(X_t) dt + Z_t dB_t, \quad X_T = \xi.$$

MRT: for $\mu \equiv 0$ we get the **martingale representation problem**:

$$dX_t = Z_t dB_t, \quad X_T = \xi.$$

BACKWARD SDE

A change of notation:

$$dY_t = -f(Y_t, Z_t) dt + Z_t dB_t, \quad t \in [0, T], \quad Y_T = \xi.$$

A *solution* is a pair (Y, Z) . The function f is called the *driver*.

Time- and uncertainty-dependence is often added:

$$dY_t = -f(t, \omega, Y_t, Z_t) dt + Z_t dB_t, \quad t \in [0, T], \quad Y_T = \xi(\omega),$$

and the ω -dependence factored through a (forward) diffusion

$$\begin{aligned} X_0 = x, \quad dX_t &= \mu(t, X_t) dt + \sigma(t, X_t) dB_t \\ dY_t &= -f(t, X_t, Y_t, Z_t) dt + Z_t dB_t, \quad Y_T = g(X_t). \end{aligned}$$

EXISTING THEORY - DIMENSION 1

Linear: BISMUT '73, (or even WENTZEL, KUNITA-WATANABE or ITÔ)

Lipschitz: PARDOUX-PENG '90

Linear-growth: LEPELTIER-SAN MARTIN '97

With reflection: EL KAROUI et al '95, CVITANIĆ-KARATZAS '96

Constrained: BUCKDAHN-HU '98, CVITANIĆ-KARATZAS-SONER '98

Quadratic: KOBYLANSKI '00

Superquadratic: DELBAEN-HU-BAO '11 - mostly negative

EXISTING THEORY - SYSTEMS

Lipschitz drivers: PARDOUX-PENG '90

Smallness: TEVZADZE '08

Quadratic global existence: PENG '99 - **open problem**

Non-existence: FREI - DOS REIS '11

Quadratic global existence - special cases:

TAN '03, JAMNESHAN-KUPPER-LUO '14,
CHERIDITO-NAM '15, HU-TANG '15

A PDE CONNECTION

A single equation: under regularity conditions, the pair (Y, Z) is a Markovian solution, i.e., $Y = v(t, B_t)$, to

$$dY_t = -f(Y_t, Z_t) dt + Z_t dB_t, \quad Y_T = g(B_T)$$

if and only if v is a **viscosity solution** to

$$v_t + \frac{1}{2} \Delta v + f(v, Dv) = 0, \quad v(T, \cdot) = g.$$

Systems: no such characterization (“if” direction when the PDE system admits a smooth solution).

no maximum principle \rightarrow no notion of a viscosity solution.

THE APPROACH OF KOBYLANSKI

Approximation: approximate both the driver f and the terminal condition g by Lipschitz functions; ensure monotonicity.

Monotone convergence: use the comparison (maximum) principle to get monotonicity of solutions

BMO-bounds: use the quadratic growth of f to get uniform bounds on the approximations to Z ; **exponential transforms**

$H_t^\alpha = \exp(\alpha Y_t)$ is a submartingale for large enough α ,

since

$$dH_t^\alpha = \alpha H_t^\alpha Z_t dB_t + \alpha H_t^\alpha \left(\frac{1}{2} \alpha Z_t^2 - f(Y_t, Z_t) \right) dt$$

Unfortunately: this will not work for systems for two reasons:

1. There is no comparison principle for systems
2. The exponential transform no longer works.

OUR SETUP

The driving diffusion: let X be a uniformly-elliptic inhomogeneous diffusion on \mathbb{R}^d with (globally) Lipschitz and bounded coefficients.

Markovian solutions: a pair $v : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^N$, $w : [0, T] \times \mathbb{R}^{N \times d}$ of Borel functions such that $Y := v(\cdot, X)$ is a **continuous semimartingale**, and

$$g(X_T) = Y_t - \int_t^T f(s, X_s, Y_s, Z_s) ds + \int_t^T Z_s dB_s,$$

where $Z := w(\cdot, X)$.

Variants: *bounded* or *(locally) Hölderian* solutions (when v has that property) or a *bmo-solution* (when $w(t, X_t)$ is in bmo).

A SUBSTITUTE FOR THE EXPONENTIAL TRANSFORM

Set $\langle \mathbf{z}, \mathbf{z} \rangle_{a(t,x)} = \mathbf{z}a(t,x)\mathbf{z}^T$, where $a = \sigma\sigma^T$ (double the coefficient matrix for the second-order part of the generator of X):

Definition: Given a constant $c > 0$, a function $h \in C^2(\mathbb{R}^N)$ is called a *c-Lyapunov function* for f if $h(\mathbf{0}) = 0$, $Dh(\mathbf{0}) = \mathbf{0}$, and there exists a constant k such that

$$\frac{1}{2}D^2h(\mathbf{y}) : \langle \mathbf{z}, \mathbf{z} \rangle_{a(t,x)} - Dh(\mathbf{y})f(t,x,\mathbf{y},\mathbf{z}) \geq |\mathbf{z}|^2 - k \quad (1)$$

for all $(t,x,\mathbf{y},\mathbf{z}) \in [0,T] \times \mathbb{R}^d \times \mathbb{R}^N \times \mathbb{R}^{N \times d}$, with $|\mathbf{y}| \leq c$.

Intuitively: $h(Y_t) + kt$ must be a ‘very strict’ submartingale, whenever Y is a solution. As mentioned before, for $N = 1$, $h(y) = e^{\alpha y}$, for large-enough α .

THE MAIN RESULT

Theorem. Let X be a uniformly elliptic diffusion with bounded, Lipschitz coefficients, and f be a continuous driver of (at-most) quadratic growth in z . Suppose that there exists a constant $c > 0$ such that

- ▶ g is bounded and in C^α ,
- ▶ f admits a c -Lyapunov function, and
- ▶ Y is “a-priori bounded” by c .

Then the BSDE system

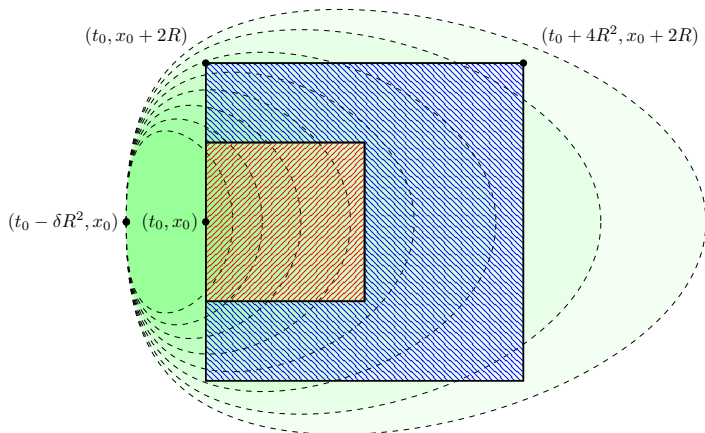
$$dY_t = -f(t, X_t, Y_t, Z_t) dt + Z_t dB_t, \quad Y_T = g(B_T),$$

has a Hölderian solution (v, w) , with $\int Z dB$ a BMO-martingale and $w = Dv$, in the distributional sense on $(0, T) \times \mathbb{R}^d$.

This solution is, moreover, unique in the class of all Markovian solutions if f is y -independent and

$$|f(t, x, z_2) - f(t, x, z_1)| \leq C(|z_1| + |z_2|) |z_2 - z_1|.$$

A PEEK INTO THE PROOF



$$\iint_{\text{red}} |Dv|^2 \leq C \iint_{\text{blue}} |Dv|^2 + R^{2\alpha}$$

We use the “hole filling” method (WIDMAN '76) and its variants (STRUWE '81, BENSOUSSAN-FREHSE, '02) - and apply it to get Campanato (and therefore Hölder) a-priori estimates.

THE BENSOUSSAN-FREHSE (BF) CONDITION

Proposition. If f admits a decomposition

$$f(t, x, \mathbf{y}, \mathbf{z}) = \text{diag}(\mathbf{z} l(t, x, \mathbf{y}, \mathbf{z})) + \mathbf{q}(t, x, \mathbf{y}, \mathbf{z}) + \mathbf{s}(t, x, \mathbf{y}, \mathbf{z}) + \mathbf{k}(t, x),$$

with

$$|l(t, x, \mathbf{y}, \mathbf{z})| \leq C(1 + |\mathbf{z}|), \quad (\text{quadratic-linear})$$

$$|q^i(t, x, \mathbf{y}, \mathbf{z})| \leq C(1 + \sum_{j=1}^i |z^j|^2), \quad (\text{quadratic-triangular})$$

$$|s(t, x, \mathbf{y}, \mathbf{z})| \leq \kappa(|\mathbf{z}|), \quad \lim_{z \rightarrow \infty} \frac{\kappa(z)}{z^2} = 0, \quad (\text{subquadratic})$$

$$\mathbf{k} \in \mathbb{L}^\infty([0, T] \times \mathbb{R}^d), \quad (\mathbf{z}\text{-independent}),$$

Then a c -Lyapunov function exists for each $c > 0$.

Extensions: an **approximate** decomposition will do, as well. To the best of our knowledge, **all** systems solved in the literature satisfy the (BF) condition (in \mathbf{z} -dependence).

STOCHASTIC EQUILIBRIA IN INCOMPLETE MARKETS

Setup: $\{\mathcal{F}_t\}_{t \in [0, T]}$ generated by two independent BMs B and W

Price: $dS_t^\lambda = \lambda_t dt + \sigma_t dB_t + \boxed{0 dW_t}$ (WLOG $\sigma_t \equiv 1!$)

Agents: $U^i(x) = -\exp(-x/\delta^i)$, $E^i \in \mathbb{L}^0(\mathcal{F}_T)$, $i = 1, \dots, I$

Demand: $\hat{\pi}^{\lambda, i} := \operatorname{argmax}_{\pi \in \mathcal{A}^\lambda} \mathbb{E} \left[U^i \left(\int_0^T \pi_u dS_u^\lambda + E^i \right) \right]$.

Goal: Is there an *equilibrium market price of risk* λ , i.e., does there exist a process λ such that the *clearing conditions*

$$\sum_{i=1}^I \hat{\pi}^{\lambda, i} = 0$$

hold?

STOCHASTIC EQUILIBRIA IN INCOMPLETE MARKETS

A characterization: KARDARAS, XING and Ž, '15, give the following characterization: a process $\lambda \in \text{bmo}$ is an equilibrium market price of risk *if and only if* it admits a representation of the form

$$A[\boldsymbol{\mu}] := \sum_{i=1}^N \alpha_i \mu^i,$$

for some solution $(\boldsymbol{\mu}, \boldsymbol{\nu}, \mathbf{Y}) \in \text{bmo} \times \text{bmo} \times \mathcal{S}^\infty$ of

$$\begin{cases} dY_t^i = \mu_t^i dB_t + \nu_t^i dW_t + \left(\frac{1}{2}(\nu_t^i)^2 - \frac{1}{2}A[\boldsymbol{\mu}]_t^2 + A[\boldsymbol{\mu}]\mu_t^i \right) dt, \\ Y_T^i = G^i, \quad i = 1, \dots, I, \end{cases}$$

where $\alpha^i = \delta^i / (\sum_j \delta^j)$, $G^i = E^i / \delta^i$.

Theorem (XING, Ž.) If there exists a regular enough function g and a diffusion X such that $G^i = g^i(X_T)$, for all i , then a stochastic equilibrium exists and is unique in the class of Markovian solutions.

MARTINGALES ON MANIFOLDS

Γ -martingales: Let M be an N -dimensional differentiable manifold endowed with an affine connection Γ . A continuous semimartingale \mathbf{Y} on M is called a Γ -martingale if

$$f(\mathbf{Y}_t) - \frac{1}{2} \int_0^t \text{Hess} f(d\mathbf{Y}_s, d\mathbf{Y}_s), \quad t \in [0, T],$$

is a local martingale for each smooth $f : M \rightarrow \mathbb{R}$, where

$$(\text{Hess} f)_{ij}(\mathbf{y}) = D_{ij}f(\mathbf{y}) - \sum_{k=1}^N \Gamma_{ij}^k(\mathbf{y}) D_k f(\mathbf{y}).$$

A coordinate representation: By Itô's formula, \mathbf{Y} is a Γ -martingale if and only if its coordinate representation has the following form

$$dY_t^k = -f^k(\mathbf{Y}_t, \mathbf{Z}_t) dt + \mathbf{Z}_t^k dW_t$$

where $f^k(\mathbf{y}, \mathbf{z}) = \frac{1}{2} \sum_{i,j=1}^d \Gamma_{ij}^k(\mathbf{y}) (\mathbf{z}^i)^\top \mathbf{z}^j$.

MARTINGALES ON MANIFOLDS

A Problem: Given an N -dimensional Brownian motion B and an M -valued random variable ξ , construct a Γ -martingale Y with $Y_T = \xi$.

Solution: Easy in the Euclidean case - we filter $Y_t = \mathbb{E}[\xi | \mathcal{F}_t]$. In general, solution may not exist. Under various conditions, such processes were constructed by DARLING '95 and BLACHE '05, '06.

Our contribution: Taken together, the **existence of a Lyapunov function** and **a-priori boundedness** are (essentially) equivalent to the existence of a so-called doubly-convex function h on a neighborhood of a support of ξ .

Conversely, this sheds new light on the meaning of c -Lyapunov functions: loosely speaking - they play the role of convex functions, but in the geometry dictated by f .

Sretan rodendan, Yannis!