## MODERN GEOMETRY II: PROBLEM SET 1 Due Monday, February 21

**Problem 1:** If  $\theta^i$  is the i'th component of the canonical 1-form  $\theta$  on a frame

bundle F(M), and  $s: U \to \pi^{-1}(U)$  is the local section over a coordinate patch U given by the coordinate frame, show that, for Y a vector field on U,  $s^*\theta^i(Y)$  gives the i'th component of Y with respect to the coordinate frame basis.

Problem 2: Show that

 $\nabla \theta = \Theta$ 

where  $\nabla$  is the covariant differential on  $\mathbf{R}^n$  valued forms,  $\theta$  is the canonical 1-form, and  $\Theta$  is the torsion 2-form.

**Problem 3:** Let  $B(\zeta)$ , for  $\zeta \in \mathbb{R}^n$  be the horizontal vector field defined in class. Show that

a) If  $\zeta \neq 0$ ,  $B(\zeta)$  is a nowhere zero vector field on F(M). b)  $(R_g)_*(B(\zeta)) = B(g^{-1}\zeta)$ , where  $g \in GL(n, \mathbf{R})$  and  $R_g$  is the right action by g on F(M).

**Problem 4:** If  $X_j$  is the j-th component of a coordinate frame on a coordinate patch  $U \subset M$ , and  $\Gamma^i_{jk}$  are the Christoffel symbols of a connection on F(M)in the coordinates given by U, show that the horizontal lift of  $X_j$  to  $\pi^{-1}(U)$  is given by

$$X_j^{horiz} = \frac{\partial}{\partial x^j} - \sum_{i,k,l} \Gamma_{jk}^i X_l^k \frac{\partial}{\partial X_l^i}$$

Here  $(x^i, X_k^j)$  are the local coordinates on  $\pi^{-1}(U)$  defined in class.

**Problem 5:** If one has two coordinate patches: U, with coordinates  $x^i$ , and  $\tilde{U}$  with coordinates  $\tilde{x}^i$ , show that on the overlap of the two patches the Christoffel symbols are related by:

$$\tilde{\Gamma}^{\alpha}_{\beta\gamma} = \sum_{i,j,k} \Gamma^{i}_{jk} \frac{\partial x^{j}}{\partial \tilde{x}^{\beta}} \frac{\partial x^{k}}{\partial \tilde{x}^{\gamma}} \frac{\partial \tilde{x}^{\alpha}}{\partial x^{i}} + \sum_{i} \frac{\partial^{2} x^{i}}{\partial \tilde{x}^{\beta} \partial \tilde{x}^{\gamma}} \frac{\partial \tilde{x}^{\alpha}}{\partial x^{i}}$$

## Problem 6:

If the components  $R^i_{jkl}$  of the curvature tensor with respect to a coordinate frame  $X_i$  are defined by

$$R(X_j, X_l)X_j = \sum_i R^i_{jkl}X_i$$

show that

$$R^{i}_{jkl} = \frac{\partial}{\partial x^{k}} \Gamma^{i}_{lj} - \frac{\partial}{\partial x^{l}} \Gamma^{i}_{kj} + \sum_{m} (\Gamma^{m}_{lj} \Gamma^{i}_{km} - \Gamma^{m}_{kj} \Gamma^{i}_{lm})$$